

**Christian Laugier
Raja Chatila (Eds.)**

Autonomous Navigation in Dynamic Environments

Autonomous Navigation In Dynamic Environments

Springer Tracts In Advanced Robotics

Monica Sebillo



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Recent Advances in Mobile Robotics Andon Topalov,2011-12-14 Mobile robots are the focus of a great deal of current research in robotics Mobile robotics is a young multidisciplinary field involving knowledge from many areas including electrical electronic and mechanical engineering computer cognitive and social sciences Being engaged in the design of automated systems it lies at the intersection of artificial intelligence computational vision and robotics Thanks to the numerous researchers sharing their goals visions and results within the community mobile robotics is becoming a very rich and stimulating area The book Recent Advances in Mobile Robotics addresses the topic by integrating contributions from many researchers around the globe It emphasizes the computational methods of programming mobile robots rather than the methods of constructing the hardware Its content reflects different complementary aspects of theory and practice which have recently taken place We believe that it will serve as a valuable handbook to those who work in research and development of mobile robots

Parallel Computing Technologies Victor Malyshev,2009-08-04 This book constitutes the proceedings of the 10th International Conference on Parallel Computing Technologies PaCT 2009 held in Novosibirsk Russia on August 31 September 4 2009 The 34 full papers presented together with 2 invited papers and 7 poster papers were carefully reviewed and selected from 72 submissions The papers are organized in topical sections on models of parallel computing methods and algorithms fine grained parallelism parallel programming tools and support and applications

Visual Information Systems. Web-Based Visual Information Search and Management Monica Sebillio,2008-08-28 This book constitutes the thoroughly refereed proceedings of the 10th International Conference on Visual Information Systems VISUAL 2008 held in Salerno Italy September 11 12 2008 The 35 papers presented in this volume together with 3 keynote speeches were carefully reviewed and selected from 58 submissions The topics covered are information and data visualization advances techniques for visual information management mobile visual information systems image and video indexing and retrieval applications of visual information systems and industrial experiences

Mixed Reality and Gamification for Cultural Heritage Marinos Ioannides,Nadia Magnenat-Thalmann,George Papagiannakis,2017-04-26 This volume on virtual and augmented reality VR AR and gamification for cultural heritage offers an insightful introduction to the theories development recent applications and trends of the enabling technologies for mixed reality and gamified interaction in cultural heritage and creative industries in general It has two main goals serving as an introductory textbook to train beginning and experienced researchers in the field of interactive digital cultural heritage and

offering a novel platform for researchers in and across the culturally related disciplines To this end it is divided into two sections following a pedagogical model developed by the focus group of the first EU Marie S Curie Fellowship Initial Training Network on Digital Cultural Heritage ITN DCH Section I describes recent advances in mixed reality enabling technologies while section II presents the latest findings on interaction with 3D tangible and intangible digital cultural heritage The sections include selected contributions from some of the most respected scholars researchers and professionals in the fields of VR AR gamification and digital heritage This book is intended for all heritage professionals researchers lecturers and students who wish to explore the latest mixed reality and gamification technologies in the context of cultural heritage and creative industries It pursues a pedagogic approach based on trainings conferences workshops and summer schools that the ITN DCH fellows have been following in order to learn how to design next generation virtual heritage applications systems and services

Motion Planning Xj Jing, 2008-06-01 In this book new results or developments from different research backgrounds and application fields are put together to provide a wide and useful viewpoint on these headed research problems mentioned above focused on the motion planning problem of mobile robots These results cover a large range of the problems that are frequently encountered in the motion planning of mobile robots both in theoretical methods and practical applications including obstacle avoidance methods navigation and localization techniques environmental modelling or map building methods and vision signal processing etc Different methods such as potential fields reactive behaviours neural fuzzy based methods motion control methods and so on are studied Through this book and its references the reader will definitely be able to get a thorough overview on the current research results for this specific topic in robotics The book is intended for the readers who are interested and active in the field of robotics and especially for those who want to study and develop their own methods in motion path planning or control for an intelligent robotic system

Pattern Recognition José Francisco Martínez-Trinidad, Jesús Ariel Carrasco-Ochoa, Victor Ayala Ramírez, José Arturo Olvera-López, Xiaoyi Jiang, 2016-06-15 This book constitutes the refereed proceedings of the 8th Mexican Conference on Pattern Recognition MCPR 2016 held in Guanajuato Mexico in June 2016 The 34 revised full papers presented were carefully reviewed and selected from 60 submissions The papers are organized in topical sections on computer vision and image analysis pattern recognition and artificial intelligent techniques signal processing and analysis and applications of pattern recognition

Autonomous Vehicle Navigation Lounis Adouane, 2016-04-21 Improve the Safety Flexibility and Reliability of Autonomous Navigation in Complex Environments Autonomous Vehicle Navigation From Behavioral to Hybrid Multi Controller Architectures explores the use of multi controller architectures in fully autonomous robot navigation even in highly dynamic and cluttered environments Accessible to researchers

Adaptive State × Time Lattices: A Contribution to Mobile Robot Motion Planning in Unstructured Dynamic Environments Petereit, Janko, 2017-01-20 Mobile robot motion planning in unstructured dynamic environments is a challenging task Thus often suboptimal methods are employed which perform global path planning and

local obstacle avoidance separately This work introduces a holistic planning algorithm which is based on the concept of state
Transactions on Edutainment VII Zhigeng Pan, Adrian David Cheok, Wolfgang Mueller, Maiga Chang, Mingmin
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