



Automated Planning Automated Planning

Liying Dong



Automated Planning Automated Planning:

Automated Planning Malik Ghallab,Dana Nau,Paolo Traverso,2004-05-21 Automated planning technology now plays a significant role in a variety of demanding applications ranging from controlling space vehicles and robots to playing the game of bridge These real world applications create new opportunities for synergy between theory and practice observing what works well in practice leads to better theories of planning and better theories lead to better performance of practical applications Automated Planning mirrors this dialogue by offering a comprehensive up to date resource on both the theory and practice of automated planning The book goes well beyond classical planning to include temporal planning resource scheduling planning under uncertainty and modern techniques for plan generation such as task decomposition propositional satisfiability constraint satisfaction and model checking The authors combine over 30 years experience in planning research and development to offer an invaluable text to researchers professionals and graduate students Provides a thorough understanding of AI planning theory and practice and how they relate to each other Covers all the contemporary topics of planning as well as important practical applications of planning such as model checking and game playing Presents case studies and applications in planning engineering space robotics CAD CAM process control emergency operations and games Provides lecture notes examples of programming assignments pointers to downloadable planning systems and related information online

A Concise Introduction to Models and Methods for Automated Planning Hector Geffner,Blai Bonet,2013-06-01 Planning is the model based approach to autonomous behavior where the agent behavior is derived automatically from a model of the actions sensors and goals The main challenges in planning are computational as all models whether featuring uncertainty and feedback or not are intractable in the worst case when represented in compact form In this book we look at a variety of models used in AI planning and at the methods that have been developed for solving them The goal is to provide a modern and coherent view of planning that is precise concise and mostly self contained without being shallow For this we make no attempt at covering the whole variety of planning approaches ideas and applications and focus on the essentials The target audience of the book are students and researchers interested in autonomous behavior and planning from an AI engineering or cognitive science perspective Table of Contents Preface Planning and Autonomous Behavior Classical Planning Full Information and Deterministic Actions Classical Planning Variations and Extensions Beyond Classical Planning Transformations Planning with Sensing Logical Models MDP Planning Stochastic Actions and Full Feedback POMDP Planning Stochastic Actions and Partial Feedback Discussion Bibliography Author s Biography

Automated Planning Malik Ghallab,Dana Nau,Paolo Traverso,2004-05-03 Publisher Description **Automated Planning and Acting** Malik Ghallab,Dana Nau,Paolo Traverso,2016-08-09 Autonomous AI systems need complex computational techniques for planning and performing actions Planning and acting require significant deliberation because an intelligent system must coordinate and integrate these activities in order to act effectively in the real world This book

presents a comprehensive paradigm of planning and acting using the most recent and advanced automated planning techniques. It explains the computational deliberation capabilities that allow an actor, whether physical or virtual, to reason about its actions, choose them, organize them purposefully, and act deliberately to achieve an objective. Useful for students, practitioners, and researchers, this book covers state-of-the-art planning techniques, acting techniques, and their integration, which will allow readers to design intelligent systems that are able to act effectively in the real world.

Automated Planning and Scheduling Fouad Sabry, 2023-07-06

What Is Automated Planning and Scheduling? Automated planning and scheduling is a subfield of artificial intelligence that focuses on the formulation of strategies or action sequences often for the purpose of being carried out by intelligent agents, autonomous robots, and unmanned vehicles. Automated planning and scheduling is sometimes referred to as simply AI planning at times. In contrast to traditional control and classification problems, these problems have complicated solutions that need to be discovered and optimized in multidimensional space. Planning is closely connected to the philosophy of decision making.

How You Will Benefit I: Insights and validations about the following topics: Chapter 1: Automated planning and scheduling; Chapter 2: Applications of artificial intelligence; Chapter 3: Actor model; Chapter 4: Scheduling computing; Chapter 5: Constraint satisfaction problem; Chapter 6: Action description language; Chapter 7: Strategy game theory; Chapter 8: Reactive planning; Chapter 9: Backward chaining; Chapter 10: Forward chaining. II: Answering the public top questions about automated planning and scheduling. III: Real world examples for the usage of automated planning and scheduling in many fields. IV: 17 appendices to explain briefly 266 emerging technologies in each industry to have 360-degree full understanding of automated planning and scheduling technologies.

Who This Book Is For: Professionals, undergraduate and graduate students, enthusiasts, hobbyists, and those who want to go beyond basic knowledge or information for any kind of automated planning and scheduling.

A Concise Introduction to Models and Methods for Automated Planning Hector Geffner, Blai Bonet, 2022-05-31

Planning is the model-based approach to autonomous behavior where the agent behavior is derived automatically from a model of the actions, sensors, and goals. The main challenges in planning are computational, as all models, whether featuring uncertainty and feedback or not, are intractable in the worst case when represented in compact form. In this book, we look at a variety of models used in AI planning and at the methods that have been developed for solving them. The goal is to provide a modern and coherent view of planning that is precise, concise, and mostly self-contained without being shallow. For this, we make no attempt at covering the whole variety of planning approaches, ideas, and applications and focus on the essentials. The target audience of the book are students and researchers interested in autonomous behavior and planning from an AI engineering or cognitive science perspective.

Table of Contents: Preface, Planning and Autonomous Behavior, Classical Planning, Full Information and Deterministic Actions, Classical Planning Variations and Extensions, Beyond Classical Planning, Transformations, Planning with Sensing, Logical Models, MDP Planning, Stochastic Actions and Full Feedback, POMDP Planning, Stochastic Actions and Partial Feedback.

Discussion Bibliography Author s Biography Automated Planning and Acting Malik Ghallab,Dana Nau,Paolo Traverso,2016-08-09 This book presents the most recent and advanced techniques for creating autonomous AI systems capable of planning and acting effectively *Efficient Automated Planning with New Formulations* Ruoyun Huang,2011 Problem solving usually strongly relies on how the problem is formulated This fact also applies to automated planning a key field in artificial intelligence research Classical planning used to be dominated by STRIPS formulation a simple model based on propositional logic In the recently introduced SAS formulation the multi valued variables naturally depict certain invariants that are missed in STRIPS make SAS have many favorable features Because of its rich structural information SAS begins to attract lots of research interest Existing works however are mostly limited to one single thing to improve heuristic functions This is in sharp contrast with the abundance of planning models and techniques in the field On the other hand although heuristic is a key part for search its effectiveness is limited Recent investigations have shown that even if we have almost perfect heuristics the number of states to visit is still exponential Therefore there is a barrier between the nice features of SAS and its applications in planning algorithms In this dissertation we have recasted two major planning paradigms state space search and planning as Satisfiability SAT with three major contributions First we have utilized SAS for a new hierarchical state space search model by taking advantage of the decomposable structure within SAS This algorithm can greatly reduce the time complexity for planning Second planning as Satisfiability is a major planning approach but it is traditionally based on STRIPS We have developed a new SAS based SAT encoding scheme SASE for planning The state space modeled by SASE shows a decomposable structure with certain components independent to others showing promising structure that STRIPS based encoding does not have Third the expressiveness of planning is important for real world scenarios thus we have also extended the planning as SAT to temporally expressive planning and planning with action costs two advanced features beyond classical planning The resulting planner is competitive to state of the art planners in terms of both quality and performance Overall our work strongly suggests a shifting trend of planning from STRIPS to SAS and shows the power of formulating planning problems as Satisfiability Given the important roles of both classical planning and temporal planning our work will inspire new developments in other advanced planning problem domains **Automated Planning for Robotics** Erez Karpas,2020 Modern robots are increasingly capable of performing basic activities such as localization navigation and motion planning However for a robot to be considered intelligent we would like it to be able to automatically combine these capabilities in order to achieve a high level goal The field of automated planning sometimes called AI planning deals with automatically synthesizing plans that combine basic actions to achieve a high level goal In this article we focus on the intersection of automated planning and robotics and discuss some of the challenges and tools available to employ automated planning in controlling robots We review different types of planning formalisms and discuss their advantages and limitations especially in the context of planning robot actions We conclude with a brief guide aimed at

helping roboticists choose the right planning model to endow a robot with planning capabilities **An Introduction to the Planning Domain Definition Language** Patrik Haslum,Nir Lipovetzky,Daniele Magazzeni,Christian Muise,2019-04-02

Planning is the branch of Artificial Intelligence AI that seeks to automate reasoning about plans most importantly the reasoning that goes into formulating a plan to achieve a given goal in a given situation AI planning is model based a planning system takes as input a description or model of the initial situation the actions available to change it and the goal condition to output a plan composed of those actions that will accomplish the goal when executed from the initial situation The Planning Domain Definition Language PDDL is a formal knowledge representation language designed to express planning models Developed by the planning research community as a means of facilitating systems comparison it has become a de facto standard input language of many planning systems although it is not the only modelling language for planning Several variants of PDDL have emerged that capture planning problems of different natures and complexities with a focus on deterministic problems The purpose of this book is two fold First we present a unified and current account of PDDL covering the subsets of PDDL that express discrete numeric temporal and hybrid planning Second we want to introduce readers to the art of modelling planning problems in this language through educational examples that demonstrate how PDDL is used to model realistic planning problems The book is intended for advanced students and researchers in AI who want to dive into the mechanics of AI planning as well as those who want to be able to use AI planning systems without an in depth explanation of the algorithms and implementation techniques they use

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Automated Planning Automated Planning Introduction

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