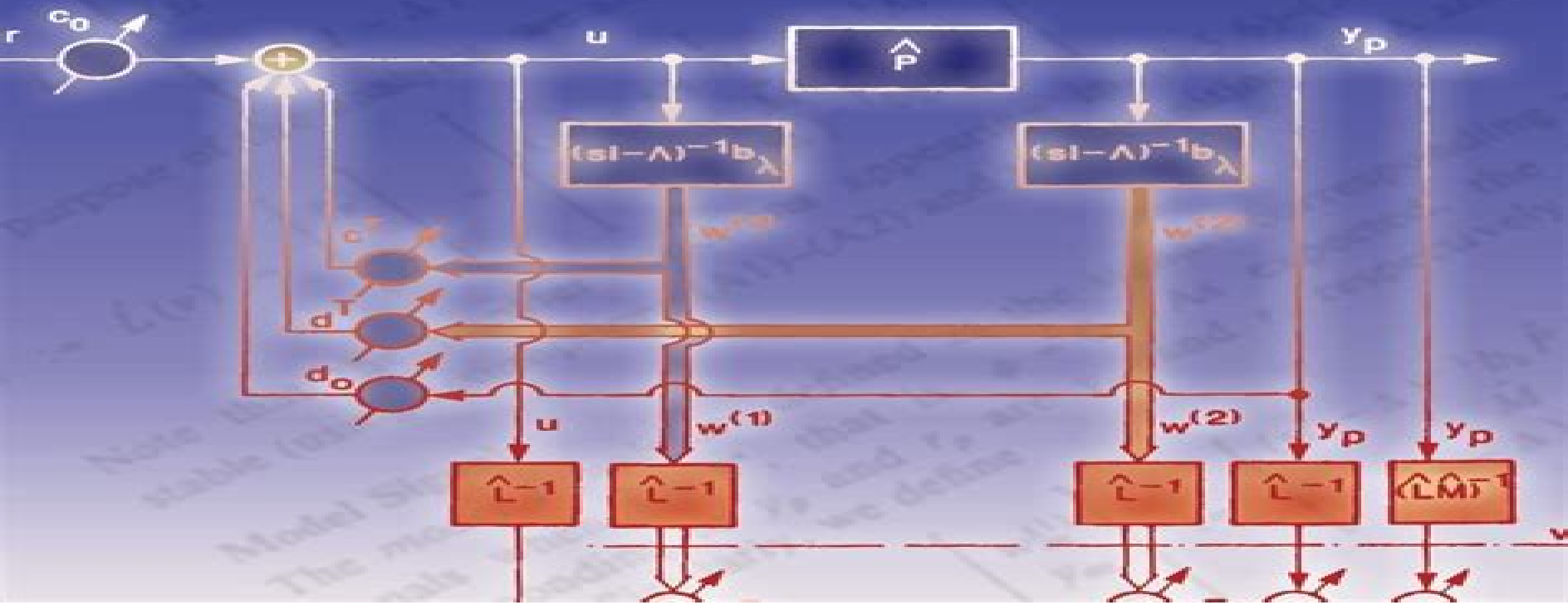


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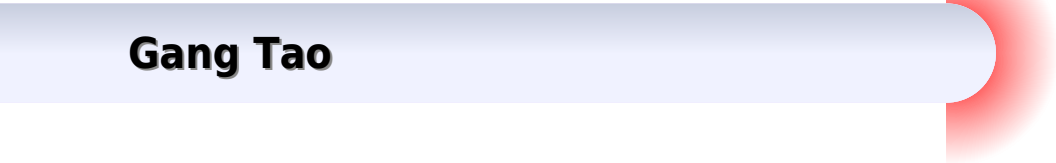
Adaptive Control

STABILITY, CONVERGENCE AND ROBUSTNESS



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Adaptive Control Shankar Sastry, Marc Bodson, 2011-01-01 This volume surveys the major results and techniques of analysis in the field of adaptive control Focusing on linear continuous time single input single output systems the authors offer a clear conceptual presentation of adaptive methods enabling a critical evaluation of these techniques and suggesting avenues of further development 1989 edition Control of Complex Systems Kyriakos Vamvoudakis, Sarangapani Jagannathan, 2016-07-27 In the era of cyber physical systems the area of control of complex systems has grown to be one of the hardest in terms of algorithmic design techniques and analytical tools The 23 chapters written by international specialists in the field cover a variety of interests within the broader field of learning adaptation optimization and networked control The editors have grouped these into the following 5 sections Introduction and Background on Control Theory Adaptive Control and Neuroscience Adaptive Learning Algorithms Cyber Physical Systems and Cooperative Control Applications The diversity of the research presented gives the reader a unique opportunity to explore a comprehensive overview of a field of great interest to control and system theorists This book is intended for researchers and control engineers in machine learning adaptive control optimization and automatic control systems including Electrical Engineers Computer Science Engineers Mechanical Engineers Aerospace Automotive Engineers and Industrial Engineers It could be used as a text or reference for advanced courses in complex control systems Collection of chapters from several well known professors and researchers that will showcase their recent work Presents different state of the art control approaches and theory for complex systems Gives algorithms that take into consideration the presence of modelling uncertainties the unavailability of the model the possibility of cooperative non cooperative goals and malicious attacks compromising the security of networked teams Real system examples and figures throughout make ideas concrete Includes chapters from several well known professors and researchers that showcases their recent work Presents different state of the art control approaches and theory for complex systems Explores the presence of modelling uncertainties the unavailability of the model the possibility of cooperative non cooperative goals and malicious attacks compromising the security of networked teams Serves as a helpful reference for researchers and control engineers working with machine learning adaptive control and automatic control systems

Advanced Autonomous Vehicle Design for Severe Environments V.V. Vantsevich, M.V. Blundell, 2015-10-20 Classical vehicle dynamics which is the basis for manned ground vehicle design has exhausted its potential for providing novel design concepts to a large degree At the same time unmanned ground vehicle UGV dynamics is still in its infancy and is currently being developed using general analytical dynamics principles with very little input from actual vehicle dynamics theory This technical book presents outcomes from the NATO Advanced Study Institute ASI Advanced Autonomous Vehicle Design for Severe Environments held in Coventry UK in July 2014 The ASI provided a platform for world class professionals to meet and discuss leading edge research engineering accomplishments and future trends in manned and unmanned ground vehicle

dynamics terrain mobility and energy efficiency The outcomes of this collective effort serve as an analytical foundation for autonomous vehicle design Topics covered include historical aspects pivotal accomplishments and the analysis of future trends in on and off road manned and unmanned vehicle dynamics terramechanics soil dynamic characteristics uncertainties and stochastic characteristics of vehicle environment interaction for agile vehicle dynamics modeling new methods and techniques in on line control and learning for vehicle autonomy fundamentals of agility and severe environments mechatronics and cyber physics issues of agile vehicle dynamics to design for control energy harvesting and cyber security and case studies of agile and inverse vehicle dynamics and vehicle systems design including optimisation of suspension and driveline systems The book targets graduate students who desire to advance further in leading edge vehicle dynamics topics in manned and unmanned ground vehicles PhD students continuing their research work and building advanced curricula in academia and industry and researchers in government agencies and private companies

Robust Adaptive Control Petros A. Ioannou, Jing Sun, 2012-12-19 Presented in a tutorial style this text reduces the confusion and difficulty in grasping the design analysis and robustness of a wide class of adaptive controls for continuous time plants The treatment unifies simplifies and explains most of the techniques for designing and analyzing adaptive control systems Excellent text and authoritative reference

Stable Adaptive Systems Kumpati S. Narendra, Anuradha M. Annaswamy, 2012-07-12 This graduate level text focuses on the stability of adaptive systems and offers a thorough understanding of the global stability properties essential to designing adaptive systems Its self contained unified presentation of well known results establishes the close connections between seemingly independent developments in the field Prerequisites include a knowledge of linear algebra and differential equations as well as a familiarity with basic concepts in linear systems theory The first chapter sets the tone for the entire book introducing basic concepts and tracing the evolution of the field from the 1960s through the 1980s The first seven chapters are accessible to beginners and the final four chapters are geared toward more advanced research oriented students Problems ranging in complexity from relatively easy to quite difficult appear throughout the text Topics include results in stability theory that emphasize incidents directly relevant to the study of adaptive systems the stability properties of adaptive observers and controllers the important concept of persistent excitation the use of error models in systems analysis areas of intense research activity and five detailed case studies of systems in which adaptive control has proved successful

Adaptive Control Karl J. Åström, Björn Wittenmark, 2013-04-26 Suitable for advanced undergraduates and graduate students this overview introduces theoretical and practical aspects of adaptive control with emphasis on deterministic and stochastic viewpoints 1995 edition

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Positive real transfer functions Foundations of Adaptive Control Petar V. Kokotovic, 2014-03-12 The 1990 Grainger Lectures delivered at the University of Illinois Urbana Champaign September 28 October 1 1990 were devoted to a critical reexamination of the foundations of adaptive control In this volume the lectures are expanded by most recent developments and solutions for some long standing open problems Concepts and approaches presented are both novel and of fundamental importance for adaptive control research in the 1990s The papers in Part I present unifications reappraisals and new results on tunability convergence and robustness of adaptive linear control whereas the papers in Part II formulate new problems in adaptive control of nonlinear systems and solve them without any linear constraints imposed on the nonlinearities

Adaptive Control Design and Analysis Gang Tao, 2003-07-09 A systematic and unified presentation of the fundamentals of adaptive control theory in both continuous time and discrete time Today adaptive control theory has grown to be a rigorous and mature discipline As the advantages of adaptive systems for developing advanced applications grow apparent adaptive control is becoming more popular in many fields of engineering and science Using a simple balanced and harmonious style this book provides a convenient introduction to the subject and improves one's understanding of adaptive control theory Adaptive Control Design and Analysis features Introduction to systems and control Stability operator norms and signal convergence Adaptive parameter estimation State feedback adaptive control designs Parametrization of state observers for adaptive control Unified continuous and discrete time adaptive control L1 a robustness theory for adaptive systems Direct and indirect adaptive control designs Benchmark comparison study of adaptive control designs Multivariate adaptive control Nonlinear adaptive control Adaptive compensation of actuator nonlinearities End of chapter discussion problems and advanced topics As either a textbook or reference this self contained tutorial of adaptive control design and analysis is ideal for practicing engineers researchers and graduate students alike *RISE-Based Robust and Adaptive Control of Nonlinear Systems* Parag Patre, Nicholas Fischer, William MacKunis, Warren E. Dixon, 2016-01-06

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