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Overall, bibliographic control is the backbone of library science, facilitating the organization, management, and access to information in libraries, both traditional and digital.

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**Yasundo Takahashi, Michael Jerome
Rabins, David M. Auslander**



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Stability and Control of Dynamical Systems with Applications Derong Liu, Panos J. Antsaklis, 2003-06-24 It is with great pleasure that I offer my reflections on Professor Anthony N Michel's retirement from the University of Notre Dame I have known Tony since 1984 when he joined the University of Notre Dame's faculty as Chair of the Department of Electrical Engineering Tony has had a long and outstanding career As a researcher he has made important contributions in several areas of systems theory and control theory especially stability analysis of large scale dynamical systems The numerous awards he received from the professional societies particularly the Institute of Electrical and Electronics Engineers IEEE are a testament to his accomplishments in research He received the IEEE Control Systems Society's Best Transactions Paper Award 1978 and the IEEE Circuits and Systems Society's Guillemin-Cauer Prize Paper Award 1984 and Myril B Reed Outstanding Paper Award 1993 among others In addition he was a Fulbright Scholar 1992 and received the Alexander von Humboldt-Forschungspreis Alexander von Humboldt Research Award for Senior U.S. Scientists from the German government 1997 To date he has written eight books and published over 150 archival journal papers Tony is also an effective administrator who inspires high academic standards

Dynamical Systems and Control Firdaus E. Udwadia, H.I. Weber, George Leitmann, 2004-05-10 The 11th International Workshop on Dynamics and Control brought together scientists and engineers from diverse fields and gave them a venue to develop a greater understanding of this discipline and how it relates to many areas in science engineering economics and biology The event gave researchers an opportunity to investigate ideas and techniques

Optimization and Control of Dynamic Systems Henryk Górecki, 2017-07-26 This book offers a comprehensive presentation of optimization and polyoptimization methods The examples included are taken from various domains mechanics electrical engineering economy informatics and automatic control making the book especially attractive With the motto from general abstraction to practical examples it presents the theory and applications of optimization step by step from the function of one variable and functions of many variables with constraints to infinite dimensional problems calculus of variations a continuation of which are optimization methods of dynamical systems that is dynamic programming and the maximum principle and finishing with polyoptimization methods It includes numerous practical examples e.g. optimization of hierarchical systems optimization of time delay systems rocket stabilization modeled by balancing a stick on a finger a simplified version of the journey to the moon optimization of hybrid

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