



Further Advances in Unmanned Marine Vehicles

Edited by
G.N. Roberts and R. Sutton

Advances In Unmanned Marine Vehicles Advances In Unmanned Marine Vehicles

**Yang Shi,Chao Shen,Henglai
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Advances In Unmanned Marine Vehicles Advances In Unmanned Marine Vehicles:

Advances in Unmanned Marine Vehicles G.N. Roberts,R. Sutton,2006-01-31 Unmanned marine vehicles UMVs include autonomous underwater vehicles remotely operated vehicles semi submersibles and unmanned surface craft Considerable importance is being placed on the design and development of such vehicles as they provide cost effective solutions to a number of littoral coastal and offshore problems This book highlights the advanced technology that is evolving to meet the challenges being posed in this exciting and growing area of research

Further Advances in Unmanned Marine Vehicles G.N. Roberts,R. Sutton,2012-07-30 Unmanned marine vehicles UMVs is a collective term which can be used to describe autonomous underwater vehicles remotely operated vehicles semisubmersibles and unmanned surface craft These days there is considerable interest being shown in UMVs by the military civilian and scientific communities for undertaking designated missions whilst either operating autonomously and or in cooperation with other types of vehicle More and more worldwide importance is also being placed on the design and development of such vehicles as they are capable of providing cost effective solutions to a number of littoral coastal and offshore problems This new book on the subject will cover topics including Navigation guidance and control of the following unmanned marine vehicles remotely operated vehicles ROVs autonomous underwater vehicles AUVs ncluding gliders autonomous surface vehicles ASVs

Advanced Model Predictive Control for Autonomous Marine Vehicles Yang Shi,Chao Shen,Henglai Wei,Kunwu Zhang,2023-02-13 This book provides a comprehensive overview of marine control system design related to underwater robotics applications In particular it presents novel optimization based model predictive control strategies to solve control problems appearing in autonomous underwater vehicle applications These novel approaches bring unique features such as constraint handling prioritization between multiple design objectives optimal control performance and robustness against disturbances and uncertainties into the control system design They therefore form a more general framework to design marine control systems and can be widely applied Advanced Model Predictive Control for Autonomous Marine Vehicles balances theoretical rigor providing thorough analysis and developing provably correct design conditions and application perspectives addressing practical system constraints and implementation issues Starting with a fixed point positioning problem for a single vehicle and progressing to the trajectory tracking and path following problem of the vehicle and then to the coordination control of a large scale multi robot team this book addresses the motion control problems increasing their level of challenge step by step At each step related subproblems such as path planning thrust allocation collision avoidance and time constraints for real time implementation are also discussed with solutions In each chapter of this book compact and illustrative examples are provided to demonstrate the design and implementation procedures As a result this book is useful for both theoretical study and practical engineering design and the tools provided in the book are readily applicable for real world implementation

Advanced, Contemporary Control Andrzej Bartoszewicz,Jacek Kabziński,Janusz Kacprzyk,2020-06-24 This book

presents the proceedings of the 20th Polish Control Conference A triennial event that was first held in 1958 the conference successfully combines its long tradition with a modern approach to shed light on problems in control engineering automation robotics and a wide range of applications in these disciplines The book presents new theoretical results concerning the steering of dynamical systems as well as industrial case studies and worked solutions to real world problems in contemporary engineering It particularly focuses on the modelling identification analysis and design of automation systems however it also addresses the evaluation of their performance efficiency and reliability Other topics include fault tolerant control in robotics automated manufacturing mechatronics and industrial systems Moreover it discusses data processing and transfer issues covering a variety of methodologies including model predictive robust and adaptive techniques as well as algebraic and geometric methods and fractional order calculus approaches The book also examines essential application areas such as transportation and autonomous intelligent vehicle systems robotic arms mobile manipulators cyber physical systems electric drives and both surface and underwater marine vessels Lastly it explores biological and medical applications of the control theory inspired methods

Nonlinear Control of Vehicles and Robots Béla Lantos,Lőrinc Márton,2010-12-01 Nonlinear Control of Vehicles and Robots develops a unified approach to the dynamic modeling of robots in terrestrial aerial and marine environments The main classes of nonlinear systems and stability methods are summarized and basic nonlinear control methods useful in manipulator and vehicle control are presented Formation control of ground robots and ships is discussed The book also deals with the modeling and control of robotic systems in the presence of non smooth nonlinearities Robust adaptive tracking control of robotic systems with unknown payload and friction in the presence of uncertainties is treated Theoretical and practical aspects of the control algorithms under discussion are detailed Examples are included throughout the book allowing the reader to apply the control and modeling techniques in their own research and development work Some of these examples demonstrate state estimation based on the use of advanced sensors as part of the control system

Advances in Marine Environmental Protection: Challenges, Solutions and Perspectives Mehran Idris Khan,Yen-Chiang Chang,Wen-Hong Liu,2025-04-29 Environments have no boundaries and no borders Managing oceanic environments particularly the threats and risks of pollution should also consider the shared responsibility of all coastal states Emerging issues for oceanic pollution governance include global changes like rising temperature ocean acidification but also disturbances of ecosystem functioning by plastic and pollution by other emerging contaminants for example noise pollution and deep sea mining These call for efficient and sustainable prevention and restoration strategies such as such as efficient urban and industrial sewage treatment plants efficiently administered transnational marine protected areas and among others sustainable aquaculture extensive small scale fisheries Environmental protection warrants the development of interrelationships between marine sciences relevant industries and ocean governance developing internationally accepted rules and regulations for sustainable ocean management This Research Topic will explore possible new domains of ocean

governance and the marine environment from the interdisciplinary perspectives of the rule of law including the international agreement on equal conventions the Convention on Facilitation of International Maritime Traffic the Convention on the International Regulation for Preventing Collisions at Sea and International Convention for the Prevention of Pollution from Ships MARPOL

New Horizons in Evolutionary Robotics Stéphane Doncieux, Nicolas Bredeche, Jean-Baptiste Mouret, 2011-02-17 Evolutionary Algorithms EAs now provide mature optimization tools that have successfully been applied to many problems from designing antennas to complete robots and provided many human competitive results In robotics the integration of EAs within the engineer's toolbox made tremendous progress in the last 20 years and proposes new methods to address challenging problems in various setups modular robotics swarm robotics robotics with non conventional mechanics e.g. high redundancy dynamic motion multi modality etc This book takes its roots in the workshop on New Horizons in Evolutionary Design of Robots that brought together researchers from Computer Science and Robotics during the IEEE RSJ International Conference on Intelligent Robots and Systems IROS 2009 in Saint Louis USA This book features extended contributions from the workshop thus providing various examples of current problems and applications with a special emphasis on the link between Computer Science and Robotics It also provides a comprehensive and up to date introduction to Evolutionary Robotics after 20 years of maturation as well as thoughts and considerations from several major actors in the field This book offers a comprehensive introduction to the current trends and challenges in Evolutionary Robotics for the next decade

Advanced Control Methods in Marine Robotics Applications Fabio Bonsignorio, Enrica Zereik, Marco Bibuli, Kristin Ytterstad Pettersen, Oussama Khatib, 2021-06-09

Undersea Vehicles and National Needs Committee on Undersea Vehicles and National Needs, Commission on Engineering and Technical Systems, Division on Engineering and Physical Sciences, National Research Council, 1996-12-03 The United States faces decisions requiring information about the oceans in vastly expanded scales of time and space and from oceanic sectors not accessible with the suite of tools now used by scientists and engineers Advances in guidance and control communications sensors and other technologies for undersea vehicles can provide an opportunity to understand the oceans influence on the energy and chemical balance that sustains humankind and to manage and deliver resources from and beneath the sea This book assesses the state of undersea vehicle technology and opportunities for vehicle applications in science and industry It provides guidance about vehicle subsystem development priorities and describes how national research can be focused most effectively

Advances in Maritime Technology and Engineering Carlos Guedes Soares, Tiago A. Santos, 2024-05-08 Advances in Maritime Technology and Engineering comprises a collection of the papers presented at the 7th International Conference on Maritime Technology and Engineering MARTECH 2024 held in Lisbon Portugal on 14-16 May 2024 This Conference has evolved from the series of biannual national conferences in Portugal which have become an international event reflecting the internationalization of the maritime sector and its activities MARTECH 2024 is the seventh of this new series of biannual conferences This book

comprises 142 contributions that were reviewed by an International Scientific Committee Advances in Maritime Technology and Engineering is dedicated to maritime transportation ports as well as maritime safety and reliability It further comprises sections dedicated to ship design cruise ship design and to the structural aspects of ship design such as ultimate strength and composites subsea structures as pipelines and to ship building and ship repair The Proceedings in Marine Technology and Ocean Engineering series is dedicated to the publication of proceedings of peer reviewed international conferences dealing with various aspects of Marine Technology and Ocean Engineering The series includes the proceedings of the following conferences the International Maritime Association of the Mediterranean IMAM conferences the Marine Structures MARSTRUCT conferences the Renewable Energies Offshore RENEW conferences and the Maritime Technology MARTECH conferences The Marine Technology and Ocean Engineering series is also open to new conferences that cover topics on the sustainable exploration of marine resources in various fields such as maritime transport and ports usage of the ocean including coastal areas nautical activities the exploration and exploitation of mineral resources the protection of the marine environment and its resources and risk analysis safety and reliability The aim of the series is to stimulate advanced education and training through the wide dissemination of the results of scientific research

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