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Human Factors in Robots, Drones and Unmanned Systems Alexandra Medina-Borja, Krystyna Gielo-Perczak, 2024-07-24 Proceedings of the 15th International Conference on Applied Human Factors and Ergonomics and the Affiliated Conferences Nice France 24 27 July 2024 Proceedings of 2022 International Conference on Autonomous Unmanned Systems (ICAUS 2022) Wenxing Fu, Mancang Gu, Yifeng Niu, 2023-03-10 This book includes original peer reviewed research papers from the ICAUS 2022 which offers a unique and interesting platform for scientists engineers and practitioners throughout the world to present and share their most recent research and innovative ideas The aim of the ICAUS 2022 is to stimulate researchers active in the areas pertinent to intelligent unmanned systems The topics covered include but are not limited to Unmanned Aerial Ground Surface Underwater Systems Robotic Autonomous Control Navigation and Positioning Architecture Energy and Task Planning and Effectiveness Evaluation Technologies Artificial Intelligence Algorithm Bionic Technology and Its Application in Unmanned Systems The papers showcased here share the latest findings on Unmanned Systems Robotics Automation Intelligent Systems Control Systems Integrated Networks Modeling and Simulation It makes the book a valuable asset for researchers engineers and university students alike *Intelligent Unmanned Systems: Theory and Applications* Agus Budiyo, Bambang Riyanto, Endra Joelianto, 2009-03-03 The book largely represents the extended version of select papers from the International Conference on Intelligent Unmanned System ICIUS 2007 which was jointly organized by the Center for Unmanned System Studies at Institut Teknologi Bandung Artificial Muscle Research Center at Konkuk University and Institute of Bio inspired Structure and Surface Engineering Nanjing University of Aeronautics and Astronautics The joint event was the 3rd conference extending from International Conference on Emerging System Technology ICESS in 2005 and International Conference on Technology Fusion ICTF in 2006 both conducted in Seoul ICIUS 2007 was focused on both theory and application primarily covering the topics on robotics autonomous vehicles and intelligent unmanned technologies The conference was arranged into three parallel symposia with the following scope of topics Unmanned Systems Micro air vehicle Underwater vehicle Micro satellite manned aerial vehicle Multi agent systems Autonomous ground vehicle Blimp Swarm intelligence learning and control Robotics and Biomimetics Artificial muscle actuators Smart sensors Design and applications of MEMS NEMS system Intelligent robot system Evolutionary algorithm Control of biological systems AI and expert systems Biological learning control systems Neural networks Genetic algorithm Control and Intelligent System Distributed intelligence Distributed decentralized intelligent control Distributed or decentralized control methods Distributed and bedded systems Embedded intelligent control Complex systems Discrete event systems Hybrid systems Networked control systems Delay systems Fuzzy systems Identification and estimation Nonlinear systems Precision motion control Control applications Control engineering education *Proceedings of 2021 International Conference on Autonomous Unmanned Systems (ICAUS 2021)* Meiping Wu, Yifeng Niu, Mancang Gu, Jin Cheng, 2022-03-18 This book includes original peer reviewed

research papers from the ICAUS 2021 which offers a unique and interesting platform for scientists engineers and practitioners throughout the world to present and share their most recent research and innovative ideas The aim of the ICAUS 2021 is to stimulate researchers active in the areas pertinent to intelligent unmanned systems The topics covered include but are not limited to Unmanned Aerial Ground Surface Underwater Systems Robotic Autonomous Control Navigation and Positioning Architecture Energy and Task Planning and Effectiveness Evaluation Technologies Artificial Intelligence Algorithm Bionic Technology and Its Application in Unmanned Systems The papers showcased here share the latest findings on Unmanned Systems Robotics Automation Intelligent Systems Control Systems Integrated Networks Modeling and Simulation It makes the book a valuable asset for researchers engineers and university students alike Deep Learning for Unmanned Systems Anis Koubaa,Ahmad Taher Azar,2021-10-01 This book is used at the graduate or advanced undergraduate level and many others Manned and unmanned ground aerial and marine vehicles enable many promising and revolutionary civilian and military applications that will change our life in the near future These applications include but are not limited to surveillance search and rescue environment monitoring infrastructure monitoring self driving cars contactless last mile delivery vehicles autonomous ships precision agriculture and transmission line inspection to name just a few These vehicles will benefit from advances of deep learning as a subfield of machine learning able to endow these vehicles with different capability such as perception situation awareness planning and intelligent control Deep learning models also have the ability to generate actionable insights into the complex structures of large data sets In recent years deep learning research has received an increasing amount of attention from researchers in academia government laboratories and industry These research activities have borne some fruit in tackling some of the challenging problems of manned and unmanned ground aerial and marine vehicles that are still open Moreover deep learning methods have been recently actively developed in other areas of machine learning including reinforcement training and transfer meta learning whereas standard deep learning methods such as recent neural network RNN and coevolutionary neural networks CNN The book is primarily meant for researchers from academia and industry who are working on in the research areas such as engineering control engineering robotics mechatronics biomedical engineering mechanical engineering and computer science The book chapters deal with the recent research problems in the areas of reinforcement learning based control of UAVs and deep learning for unmanned aerial systems UAS The book chapters present various techniques of deep learning for robotic applications The book chapters contain a good literature survey with a long list of references The book chapters are well written with a good exposition of the research problem methodology block diagrams and mathematical techniques The book chapters are lucidly illustrated with numerical examples and simulations The book chapters discuss details of applications and future research areas *ROBOT2013: First Iberian Robotics Conference* Manuel A. Armada,Alberto Sanfeliu,Manuel Ferre,2013-11-12 The interest in robotics has remarkably augmented over recent years Novel solutions for complex and very diverse application

fields exploration intervention in severe environments assistive social personal services emergency rescue operations transportation entertainment unmanned aerial vehicles medical etc has been anticipated by means of a large progress in this area of robotics Moreover the amalgamation of original ideas and related innovations the search for new potential applications and the use of state of the art supporting technologies permit to foresee an important step forward and a significant socio economic impact of advanced robot technology in the forthcoming years In response to the technical challenges in the development of these sophisticated machines a significant research and development effort has yet to be undertaken It concerns embedded technologies for power sources actuators sensors information systems new design methods adapted control techniques for highly redundant systems as well as operational and decisional autonomy and human robot co existence This book contains the proceedings of the ROBOT 2013 FIRST IBERIAN ROBOTICS CONFERENCE and it can be said that included both state of the art and more practical presentations dealing with implementation problems support technologies and future applications A growing interest in Assistive Robotics Agricultural Robotics Field Robotics Grasping and Dexterous Manipulation Humanoid Robots Intelligent Systems and Robotics Marine Robotics has been demonstrated by the very relevant number of contributions Moreover ROBOT2013 incorporates a special session on Legal and Ethical Aspects in Robotics that is becoming a topic of key relevance This Conference will be held in Madrid 28 29 November 2013 organised by the Sociedad Espa ola para la Investigaci n y Desarrollo en Rob tica SEIDROB and by the Centre for Automation and Robotics CAR Universidad Polit cnica de Madrid UPM and Consejo Superior de Investigaciones Cient ficas CSIC along with the co operation of Grupo Tem tico de Rob tica CEA GTRob Sociedade Portuguesa de Robotica SPR and Asociaci n Espa ola de Promoci n de la Investigaci n en Agentes F sicos RedAF Intelligent Robotics and Applications Haibin Yu,Jinguo Liu,Lianqing Liu,Zhaojie Ju,Yuwan Liu,Dalin Zhou,2019-08-02 The volume set LNAI 11740 until LNAI 11745 constitutes the proceedings of the 12th International Conference on Intelligent Robotics and Applications ICIRA 2019 held in Shenyang China in August 2019 The total of 378 full and 25 short papers presented in these proceedings was carefully reviewed and selected from 522 submissions The papers are organized in topical sections as follows Part I collective and social robots human biomechanics and human centered robotics robotics for cell manipulation and characterization field robots compliant mechanisms robotic grasping and manipulation with incomplete information and strong disturbance human centered robotics development of high performance joint drive for robots modular robots and other mechatronic systems compliant manipulation learning and control for lightweight robot Part II power assisted system and control bio inspired wall climbing robot underwater acoustic and optical signal processing for environmental cognition piezoelectric actuators and micro nano manipulations robot vision and scene understanding visual and motional learning in robotics signal processing and underwater bionic robots soft locomotion robot teleoperation robot autonomous control of unmanned aircraft systems Part III marine bio inspired robotics and soft robotics materials mechanisms modelling and

control robot intelligence technologies and system integration continuum mechanisms and robots unmanned underwater vehicles intelligent robots for environment detection or fine manipulation parallel robotics human robot collaboration swarm intelligence and multi robot cooperation adaptive and learning control system wearable and assistive devices and robots for healthcare nonlinear systems and control Part IV swarm intelligence unmanned system computational intelligence inspired robot navigation and SLAM fuzzy modelling for automation control and robotics development of ultra thin film flexible sensors and tactile sensation robotic technology for deep space exploration wearable sensing based limb motor function rehabilitation pattern recognition and machine learning navigation localization Part V robot legged locomotion advanced measurement and machine vision system man machine interactions fault detection testing and diagnosis estimation and identification mobile robots and intelligent autonomous systems robotic vision recognition and reconstruction robot mechanism and design Part VI robot motion analysis and planning robot design development and control medical robot robot intelligence learning and linguistics motion control computer integrated manufacturing robot cooperation virtual and augmented reality education in mechatronics engineering robotic drilling and sampling technology automotive systems mechatronics in energy systems human robot interaction

Machine Learning for Complex and Unmanned Systems Jose Martinez-Carranza, Everardo Inzunza-Gonzalez, Enrique Efren Garcia-Guerrero, Esteban Tlelo-Cuautle, 2024-02-21 This book highlights applications that include machine learning methods to enhance new developments in complex and unmanned systems The contents are organized from the applications requiring few methods to the ones combining different methods and discussing their development and hardware software implementation The book includes two parts the first one collects machine learning applications in complex systems mainly discussing developments highlighting their modeling and simulation and hardware implementation The second part collects applications of machine learning in unmanned systems including optimization and case studies in submarines drones and robots The chapters discuss miscellaneous applications required by both complex and unmanned systems in the areas of artificial intelligence cryptography embedded hardware electronics the Internet of Things and healthcare Each chapter provides guidelines and details of different methods that can be reproduced in hardware software and discusses future research Features Provides details of applications using machine learning methods to solve real problems in engineering Discusses new developments in the areas of complex and unmanned systems Includes details of hardware software implementation of machine learning methods Includes examples of applications of different machine learning methods for future lines for research in the hot topic areas of submarines drones robots cryptography electronics healthcare and the Internet of Things This book can be used by graduate students industrial and academic professionals to examine real case studies in applying machine learning in the areas of modeling simulation and optimization of complex systems cryptography electronics healthcare control systems Internet of Things security and unmanned systems such as submarines drones and robots

Intelligent Vehicles Huiyun Li, Peng Sun, Daxin

Tian,Zhengguo Sheng,Victor Leung,Huaxia Xia,Yong Hong,2025-09-27 This book constitutes the refereed proceedings of the Second CCF Intelligent Vehicles Symposium on Intelligent Vehicles CCF CIVS 2024 held in Wuhan China during October 19 20 2024 The 31 full papers included in this book were carefully reviewed and selected from 60 submissions The papers contained in these proceedings address challenging issues in autonomous driving lidar radar camera LLM battery motor electronic control charging technology sensing location HD Maps navigation prediction planning control security vehicular networking and communication as well as the fundamentals and applications of computing **Intelligent Robotics and Applications** Xuguang Lan,Xuesong Mei,Caigui Jiang,Fei Zhao,Zhiqiang Tian,2025-01-24 The 10 volume set LNAI 15201 15210 constitutes the proceedings of the 17th International Conference on Intelligent Robotics and Applications ICIRA 2024 which took place in Xi an China during July 31 August 2 2024 The 321 full papers included in these proceedings were carefully reviewed and selected from 489 submissions They were organized in topical sections as follows Part I Innovative Design and Performance Evaluation of Robot Mechanisms Part II Robot Perception and Machine Learning Cognitive Intelligence and Security Control for Multi domain Unmanned Vehicle Systems Part III Emerging Techniques for Intelligent Robots in Unstructured Environment Soft Actuators and Sensors and Advanced Intelligent and Flexible Sensor Technologies for Robotics Part IV Optimization and Intelligent Control of Underactuated Robotic Systems and Technology and application of modular robots Part V Advanced actuation and intelligent control in medical robotics Advancements in Machine Vision for Enhancing Human Robot Interaction and Hybrid Decision making and Control for Intelligent Robots Part VI Advances in Marine Robotics Visual Linguistic Affective Agents Hybrid augmented Agents for Robotics and Wearable Robots for Assistance Augmentation and Rehabilitation of human movements Part VII Integrating World Models for Enhanced Robotic Autonomy Advanced Sensing and Control Technologies for Intelligent Human Robot Interaction and Mini Invasive Robotics for In Situ Manipulation Part VIII Robot Skill Learning and Transfer Human Robot Dynamic System Learning Modelling and Control AI Driven Smart Industrial Systems and Natural Interaction and Coordinated Collaboration of Robots in Dynamic Unstructured Environments Part IX Robotics in Cooperative Manipulation MultiSensor Fusion and Multi Robot Systems Human machine Co adaptive Interface Brain inspired intelligence for robotics Planning control and application of bionic novel concept robots and Robust Perception for Safe Driving Part X AI Robot Technology for Healthcare as a Service Computational Neuroscience and Cognitive Models for Adaptive Human Robot Interactions Dynamics and Perception of Human Robot Hybrid Systems and Robotics for Rehabilitation Innovations Challenges and Future Directions

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