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robot arm by using 3 motors we can develop the robot arm with help of 4 or 5 motors according to our design in this project we used only 3 motors for controlling robot arm the below diagram shows the robot arm arrangement

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web design analysis of a remote controlled pick and place robotic vehicle 59 fig 1 block diagram of mode of operation 3 1 4 elbow this is the joint between links b and c and it has one degree of freedom actuated by a rc servo motor it can rotate to about 180° by design by link a the motion about the elbow is actuated by a set of gear trains

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