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Algorithmic Foundations of Robotics V



<u>Algorithmic Foundations Of Robotics V Springer Tracts</u> <u>In Advanced Robotics</u>

Shasha Hu

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Chirikjian, Howie Choset, Marco Morales, Todd Murphey, 2010-02-04 This book contains selected contributions to WAFR the highly competitive meeting on the algorithmic foundations of robotics They address the unique combination of questions that the design and analysis of robot algorithms inspires Algorithmic Foundations of Robotics XIII Marco Morales, Lydia Tapia, Gildardo Sánchez-Ante, Seth Hutchinson, 2020-05-07 This book gathers the outcomes of the thirteenth Workshop on the Algorithmic Foundations of Robotics WAFR the premier event for showcasing cutting edge research on algorithmic robotics The latest WAFR held at Universidad Polit cnica de Yucat n in M rida M xico on December 9 11 2018 continued this tradition This book contains fifty four papers presented at WAFR which highlight the latest research on fundamental algorithmic robotics e g planning learning navigation control manipulation optimality completeness and complexity demonstrated through several applications involving multi robot systems perception and contact manipulation Addressing a diverse range of topics in papers prepared by expert contributors the book reflects the state of the art and outlines future directions in the field of algorithmic robotics Algorithmic Foundations of Robotics XII Ken Goldberg, Pieter Abbeel, Kostas Bekris, Lauren Miller, 2020-05-06 This book presents the outcomes of the 12th International Workshop on the Algorithmic Foundations of Robotics WAFR 2016 WAFR is a prestigious single track biennial international meeting devoted to recent advances in algorithmic problems in robotics Robot algorithms are an important building block of robotic systems and are used to process inputs from users and sensors perceive and build models of the environment plan low level motions and high level tasks control robotic actuators and coordinate actions across multiple systems However developing and analyzing these algorithms raises complex challenges both theoretical and practical Advances in the algorithmic foundations of robotics have applications to manufacturing medicine distributed robotics human robot interaction intelligent prosthetics computer animation computational biology and many other areas The 2016 edition of WAFR went back to its roots and was held in San Francisco California the city where the very first WAFR was held in 1994 Organized by Pieter Abbeel Kostas Bekris Ken Goldberg and Lauren Miller WAFR 2016 featured keynote talks by John Canny on A Guided Tour of Computer Vision Robotics Algebra and HCI Erik Demaine on Replicators Transformers and Robot Swarms Science Fiction through Geometric Algorithms Dan Halperin on From Piano Movers to Piano Printers Computing and Using Minkowski Sums and by Lydia Kavraki on 20 Years of Sampling Robot Motion Furthermore it included an Open Problems Session organized by Ron Alterovitz Florian Pokorny and Jur van den Berg There were 58 paper presentations during the three day event The organizers would like to thank the authors for their work and contributions the reviewers for ensuring the high quality of the meeting the WAFR Steering Committee led by Nancy Amato as well as WAFR's fiscal sponsor the International Federation of Robotics Research IFRR led by Oussama Khatib and Henrik Christensen WAFR 2016 was an enjoyable and memorable event Algorithmic Foundations of Robotics XIV Steven M. LaValle, Ming Lin, Timo Ojala, Dylan Shell, Jingjin Yu, 2021-02-08

Algorithmic Foundations of Robotics XIV Steven M. LaValle, Ming Lin, Timo Ojala, Dylan Shell, Jingjin Yu, 2021-02-08 This proceedings book helps bring insights from this array of technical sub topics together as advanced robot algorithms

draw on the combined expertise of many fields including control theory computational geometry and topology geometrical and physical modeling reasoning under uncertainty probabilistic algorithms game theory and theoretical computer science Intelligent robots and autonomous systems depend on algorithms that efficiently realize functionalities ranging from perception to decision making from motion planning to control The works collected in this SPAR book represent the state of the art in algorithmic robotics. They originate from papers accepted to the 14th International Workshop on the Algorithmic Foundations of Robotics WAFR traditionally a biannual single track meeting of leading researchers in the field of robotics WAFR has always served as a premiere venue for the publication of some of robotics most important fundamental and lasting algorithmic contributions ensuring the rapid circulation of new ideas Though an in person meeting was planned for June 15 17 2020 in Oulu Finland the event ended up being canceled owing to the infeasibility of international travel during the global COVID 19 crisis Algorithmic Foundations of Robotics IX David Hsu, Volkan Isler, Jean-Claude Latombe, Ming C. Lin, 2010-11-18 Robotics is at the cusp of dramatic transformation Increasingly complex robots with unprecedented autonomy are finding new applications from medical surgery to construction to home services Against this background the algorithmic foundations of robotics are becoming more crucial than ever in order to build robots that are fast safe reliable and adaptive Algorithms enable robots to perceive plan control and learn The design and analysis of robot algorithms raise new fundamental questions that span computer science electrical engineering mechanical engineering and mathematics These algorithms are also finding applications beyond robotics for example in modeling molecular motion and creating digital characters for video games and architectural simulation The Workshop on Algorithmic Foundations of Robotics WAFR is a highly selective meeting of leading researchers in the field of robot algorithms Since its creation in 1994 it has published some of the field's most important and lasting contributions This book contains the proceedings of the 9th WAFR held on December 13 15 2010 at the National University of Singapore The 24 papers included in this book span a wide variety of topics from new theoretical insights to novel applications Algorithmic Foundations of Robotics, 19??

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