

# ALTIVAR 28 Quick Reference Guide

## Keypad Operation & Reference

### Using the Keypad Display



## Menu 1 – Adjustment Menu (S E t)

| Parameter                                     | Code       | Factory Setting |
|-----------------------------------------------|------------|-----------------|
| <b>Speed Reference via the Display Module</b> |            |                 |
| PI Reference                                  | 1 - P - 1  | 100             |
| Duration of Operation                         | 1 - D - 1  | 100             |
| Acceleration Time                             | 2 - A - 1  | 3 sec           |
| Deceleration Time                             | 2 - D - 1  | 3 sec           |
| Acceleration Ramp #1                          | 2 - A - 2  | 3 sec           |
| Deceleration Ramp #2                          | 2 - D - 2  | 3 sec           |
| Low Speed                                     | 2 - L - 1  | 100             |
| High Speed                                    | 2 - H - 1  | 100             |
| Motor Full Load Current (protected)           | 1 - A - 1  | 100             |
| Optimum Low Speed Torque (voltage boost)      | 2 - L - 2  | 20              |
| Slip Compensation                             | 1 - S - 1  | 0.5 - 5.0 Hz    |
| Frequency Loop Gain                           | 1 - F - 1  | 10              |
| DC Injection Braking Current                  | 1 - B - 1  | 100             |
| DC Injection Braking Time at Standstill       | 1 - B - 2  | 100             |
| Stop Frequency                                | 1 - S - 2  | 0.10            |
| <b>Ref Frequency</b>                          |            |                 |
| PI Regulator Proportional Gain                | 1 - P - 2  | 100             |
| PI Regulator Integral Gain                    | 1 - I - 1  | 1 Hz            |
| PI Feedback Multiplication Coefficient        | 1 - F - 2  | 100             |
| PI Regulator Reverse Coefficient              | 1 - R - 1  | 100             |
| Fixed Speed 1Hz                               | 1 - F - 1  | 100             |
| Fixed Speed 2Hz                               | 1 - F - 2  | 100             |
| Fixed Speed 3Hz                               | 1 - F - 3  | 100             |
| Fixed Speed 4Hz                               | 1 - F - 4  | 100             |
| Fixed Speed 5Hz                               | 1 - F - 5  | 100             |
| Fixed Speed 6Hz                               | 1 - F - 6  | 100             |
| Fixed Speed 7Hz                               | 1 - F - 7  | 100             |
| Frequency Threshold where FO Closed           | 1 - F - 8  | 100             |
| Current Threshold where FO Closes             | 1 - F - 9  | 100             |
| Motor Thermal where FO Closes                 | 1 - F - 10 | 100             |
| Low Speed Operation Time                      | 1 - L - 1  | 0               |

## Menu 2 – Drive Menu (D r C)

| Parameter                                   | Code      | Factory Setting |
|---------------------------------------------|-----------|-----------------|
| Nominal Motor Voltage                       | 2 - V - 1 | 230/240V        |
| Nominal Motor Frequency                     | 2 - F - 1 | 50/60 Hz        |
| ACR Setting                                 | 2 - A - 1 | 100             |
| Maximum Output Frequency                    | 2 - F - 2 | 50/60 Hz        |
| Type of Voltage Mode                        | 2 - V - 2 | 100             |
| Automatic Ramp Modification for Decel       | 2 - A - 2 | 100             |
| <b>Alternate Accel/Decel Ramp Frequency</b> |           |                 |
| Carrier Switching Frequency                 | 2 - C - 1 | 4 kHz           |
| Random Carrier Frequency Modulation         | 2 - C - 2 | 100             |
| Accelerator Reset                           | 2 - A - 3 | 100             |
| Enable Output Phase Failure Fault           | 2 - E - 1 | 100             |
| Enable Low Supply Phase Failure Fault       | 2 - E - 2 | 100             |
| Collocated Stop Off Limit of Line Supply    | 2 - E - 3 | 100             |
| Enable Smooth Restart after Fault           | 2 - E - 4 | 100             |
| Carrier frequency threshold at undervoltage | 2 - E - 5 | 100             |
| Scale Factor of Output Frequency for Speed  | 2 - E - 6 | 100             |
| Return to Factory Settings                  | 2 - E - 7 | 100             |

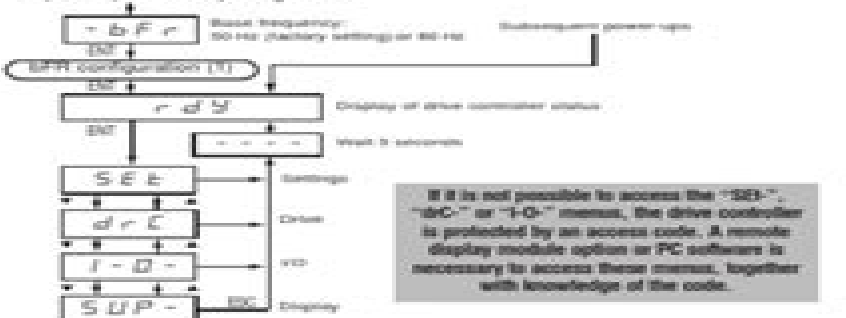
## Menu 3 – I/O Menu (I - O)

| Parameter                                             | Code      | Factory Setting |
|-------------------------------------------------------|-----------|-----------------|
| <b>Control Strategy Configuration (2-wire/3-wire)</b> |           |                 |
| 2-wire Control                                        | 3 - 2 - 1 | 100             |
| 3-wire Control                                        | 3 - 3 - 1 | 100             |
| Presence of Local Control Option                      | 3 - L - 1 | 100             |
| <b>Enable for Speeding using Remote Display</b>       |           |                 |
| Logic Input 1 Assignment                              | 3 - I - 1 | 100             |
| Logic Input 2 Assignment                              | 3 - I - 2 | 100             |
| Logic Input 3 Assignment                              | 3 - I - 3 | 100             |
| Not Assigned                                          | 3 - I - 4 | 100             |
| Reverse Rotation                                      | 3 - R - 1 | 100             |
| Running Switching                                     | 3 - R - 2 | 100             |

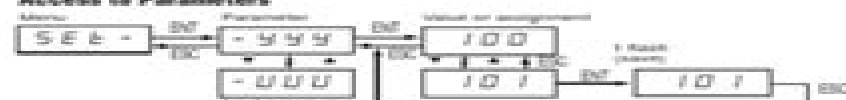
The parameters in colored boxes appear if the corresponding functions have been configured in the dir or I/O menus.

## Access to Menus

Not power up after factory configuration



## Access to Parameters



## Menu 3 – I/O Menu (I - O) continued

| Parameter                                   | Code      | Factory Setting |
|---------------------------------------------|-----------|-----------------|
| 2-wire Operation                            | 3 - 2 - 1 | 100             |
| 3-wire Operation                            | 3 - 3 - 1 | 100             |
| 4-wire Operation                            | 3 - 4 - 1 | 100             |
| 5-wire Operation                            | 3 - 5 - 1 | 100             |
| 6-wire Operation                            | 3 - 6 - 1 | 100             |
| 7-wire Operation                            | 3 - 7 - 1 | 100             |
| DC Injection Braking                        | 3 - B - 1 | 100             |
| Fast Stop                                   | 3 - F - 1 | 100             |
| Forced Local Mode                           | 3 - L - 1 | 100             |
| Fault Reset                                 | 3 - R - 1 | 100             |
| Arising Speed Reference Switching           | 3 - S - 1 | 100             |
| Analog Input Assignment of 2nd Input        | 3 - I - 2 | 100             |
| Not Assigned                                | 3 - I - 3 | 100             |
| Summing with AI                             | 3 - S - 2 | 100             |
| PI Regulator Feedback, input = parameter #1 | 3 - P - 1 | 100             |
| PI Regulator Feedback, input = AI           | 3 - P - 2 | 100             |
| Minimum Value on Analog Current Input       | 3 - C - 1 | 100             |
| Maximum Value on Analog Current Input       | 3 - C - 2 | 100             |
| Assignment of Analog Output                 | 3 - A - 1 | 100             |
| Not Assigned                                | 3 - A - 2 | 100             |
| Motor Current                               | 3 - M - 1 | 100             |
| Motor Frequency                             | 3 - F - 1 | 100             |
| Motor Torque                                | 3 - T - 1 | 100             |
| Once Pulse Supplied                         | 3 - P - 3 | 100             |
| Assignment of Output for Analog Output      | 3 - A - 2 | 100             |
| Assignment of Relay                         | 3 - R - 1 | 100             |
| Not Assigned                                | 3 - R - 2 | 100             |
| Frequency Threshold Reached                 | 3 - F - 3 | 100             |
| Current Threshold Reached                   | 3 - C - 3 | 100             |
| Speed Reference Reached                     | 3 - S - 3 | 100             |
| Motor Thermal Threshold Reached             | 3 - M - 3 | 100             |
| Drive Address via Serial Link               | 3 - A - 3 | 100             |
| Serial Link Transmission Speed              | 3 - A - 4 | 100             |

## Menu 4 – Display Menu (S U P)

| Parameter                                      | Code      | Factory Setting |
|------------------------------------------------|-----------|-----------------|
| Control Strategy Configuration (2-wire/3-wire) | 4 - 2 - 1 | 100             |
| Enable for Speeding using Remote Display       | 4 - S - 1 | 100             |
| Display Calculated value of Speed or Torque    | 4 - C - 1 | 100             |
| Display Motor Current                          | 4 - M - 1 | 100             |
| Display Motor Torque                           | 4 - T - 1 | 100             |
| Display Line Voltage                           | 4 - L - 1 | 100             |
| Display Motor Thermal State                    | 4 - M - 2 | 100             |
| Display Drive Controller Thermal State         | 4 - D - 1 | 100             |
| Display Last Fault                             | 4 - F - 1 | 100             |
| Display Drive Controller Software Version      | 4 - V - 1 | 100             |
| Access Code Protection                         | 4 - A - 1 | 100             |
| Display of Controller Status                   | 4 - S - 2 | 100             |

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# Altivar 31 Quick Reference Guide

**Richard Bailey**



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