

Yury V. Orlov
Luis T. Aguilar

Advanced H_∞ Control

Towards Nonsmooth Theory and
Applications

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AW Chickering



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Advanced H_∞ Control Yury V. Orlov, Luis T. Aguilar, 2014-02-20 This compact monograph is focused on disturbance attenuation in nonsmooth dynamic systems developing an H approach in the nonsmooth setting Similar to the standard nonlinear H approach the proposed nonsmooth design guarantees both the internal asymptotic stability of a nominal closed loop system and the dissipativity inequality which states that the size of an error signal is uniformly bounded with respect to the worst case size of an external disturbance signal This guarantee is achieved by constructing an energy or storage function that satisfies the dissipativity inequality and is then utilized as a Lyapunov function to ensure the internal stability requirements Advanced H Control is unique in the literature for its treatment of disturbance attenuation in nonsmooth systems It synthesizes various tools including Hamilton Jacobi Isaacs partial differential inequalities as well as Linear Matrix Inequalities Along with the finite dimensional treatment the synthesis is extended to infinite dimensional setting involving time delay and distributed parameter systems To help illustrate this synthesis the book focuses on electromechanical applications with nonsmooth phenomena caused by dry friction backlash and sampled data measurements Special attention is devoted to implementation issues Requiring familiarity with nonlinear systems theory this book will be accessible to graduate students interested in systems analysis and design and is a welcome addition to the literature for researchers and practitioners in these areas

Geometric Control And Nonsmooth Analysis: In Honor Of The 73rd Birthday Of H Hermes And Of The 71st Birthday Of R T Rockafellar Fabio Ancona, Alberto Bressan, Piermarco Cannarsa, Francis H Clarke, Peter R Wolenski, 2008-07-08 The aim of this volume is to provide a synthetic account of past research to give an up to date guide to current intertwined developments of control theory and nonsmooth analysis and also to point to future research directions

Nonsmooth Lyapunov Analysis in Finite and Infinite Dimensions Yury Orlov, 2020-02-08 Nonsmooth Lyapunov Analysis in Finite and Infinite Dimensions provides helpful tools for the treatment of a broad class of dynamical systems that are governed not only by ordinary differential equations but also by partial and functional differential equations Existing Lyapunov constructions are extended to discontinuous systems those with variable structure and impact by the involvement of nonsmooth Lyapunov functions The general theoretical presentation is illustrated by control related applications the nonsmooth Lyapunov construction is particularly applied to the tuning of sliding mode controllers in the presence of mismatched disturbances and to orbital stabilization of the bipedal gate The nonsmooth construction is readily extendible to the control and identification of distributed parameter and time delay systems The first part of the book outlines the relevant fundamentals of benchmark models and mathematical basics The second concentrates on the construction of nonsmooth Lyapunov functions Part III covers design and applications material This book will benefit the academic research and graduate student interested in the mathematics of Lyapunov equations and variable structure control stability analysis and robust feedback design for discontinuous systems It will also serve the practitioner working with applications of such systems

The reader should have some knowledge of dynamical systems theory but no background in discontinuous systems is required they are thoroughly introduced in both finite and infinite dimensional settings

Optimal Control: Novel Directions and Applications Daniela Tonon, Maria Soledad Aronna, Dante Kalise, 2017-09-01 Focusing on applications to science and engineering this book presents the results of the ITN FP7 SADCO network's innovative research in optimization and control in the following interconnected topics optimality conditions in optimal control dynamic programming approaches to optimal feedback synthesis and reachability analysis and computational developments in model predictive control The novelty of the book resides in the fact that it has been developed by early career researchers providing a good balance between clarity and scientific rigor Each chapter features an introduction addressed to PhD students and some original contributions aimed at specialist researchers Requiring only a graduate mathematical background the book is self contained It will be of particular interest to graduate and advanced undergraduate students industrial practitioners and to senior scientists wishing to update their knowledge

Perturbation Theory Giuseppe Gaeta, 2022-12-16 This volume in the Encyclopedia of Complexity and Systems Science Second Edition is devoted to the fundamentals of Perturbation Theory PT as well as key applications areas such as Classical and Quantum Mechanics Celestial Mechanics and Molecular Dynamics Less traditional fields of application such as Biological Evolution are also discussed Leading scientists in each area of the field provide a comprehensive picture of the landscape and the state of the art with the specific goal of combining mathematical rigor explicit computational methods and relevance to concrete applications New to this edition are chapters on Water Waves Rogue Waves Multiple Scales methods legged locomotion Condensed Matter among others while all other contributions have been revised and updated Coverage includes the theory of Poincare Birkhoff Normal Forms aspects of PT in specific mathematical settings Hamiltonian KAM theory Nekhoroshev theory and symmetric systems technical problems arising in PT with solutions convergence of series expansions diagrammatic methods parametric resonance systems with nilpotent real part PT for non smooth systems and on PT for PDEs write out this acronym partial differential equations Another group of papers is focused specifically on applications to Celestial Mechanics Quantum Mechanics and the related semiclassical PT Quantum Bifurcations Molecular Dynamics the so called choreographies in the N body problem as well as Evolutionary Theory Overall this unique volume serves to demonstrate the wide utility of PT while creating a foundation for innovations from a new generation of graduate students and professionals in Physics Mathematics Mechanics Engineering and the Biological Sciences

Nonsmooth Mechanics Bernard Brogliato, 2016-02-29 Now in its third edition this standard reference is a comprehensive treatment of nonsmooth mechanical systems refocused to give more prominence to issues connected with control and modelling It covers Lagrangian and Newton Euler systems detailing mathematical tools such as convex analysis and complementarity theory The ways in which nonsmooth mechanics influence and are influenced by well posedness analysis numerical analysis and simulation modelling and control are explained Contact impact laws stability theory and trajectory tracking control are given

detailed exposition connected by a mathematical framework formed from complementarity systems and measure differential inclusions Links are established with electrical circuits with set valued nonsmooth elements as well as with other nonsmooth dynamical systems like impulsive and piecewise linear systems Nonsmooth Mechanics third edition retains the topical structure familiar from its predecessors but has been substantially rewritten edited and updated to account for the significant body of results that have emerged in the twenty first century including developments in the existence and uniqueness of solutions impact models extension of the Lagrange Dirichlet theorem and trajectory tracking and well posedness of contact complementarity problems with and without friction Many figures both new and redrawn to improve the clarity of the presentation and examples are used to illustrate the theoretical developments Material introducing the mathematics of nonsmooth mechanics has been improved to reflect the broad range of applications interest that has developed since publication of the second edition The detail of some mathematical essentials is provided in four appendices With its improved bibliography of over 1 300 references and wide ranging coverage Nonsmooth Mechanics third edition is sure to be an invaluable resource for researchers and postgraduates studying the control of mechanical systems robotics granular matter and relevant fields of applied mathematics The book s two best features in my view are its detailed survey of the literature and its detailed presentation of many examples illustrating both the techniques and their limitations For readers interested in the field this book will serve as an excellent introductory survey Andrew Lewis in Automatica It is written with clarity contains the latest research results in the area of impact problems for rigid bodies and is recommended for both applied mathematicians and engineers Panagiotis D Panagiotopoulos in Mathematical Reviews The presentation is excellent in combining rigorous mathematics with a great number of examples allowing the reader to understand the basic concepts Hans Troger in Mathematical Abstracts i

Hybrid Systems, Optimal Control and Hybrid Vehicles Thomas J. Böhme, Benjamin Frank, 2017-02-01 This book assembles new methods showing the automotive engineer for the first time how hybrid vehicle configurations can be modeled as systems with discrete and continuous controls These hybrid systems describe naturally and compactly the networks of embedded systems which use elements such as integrators hysteresis state machines and logical rules to describe the evolution of continuous and discrete dynamics and arise inevitably when modeling hybrid electric vehicles They can throw light on systems which may otherwise be too complex or recondite Hybrid Systems Optimal Control and Hybrid Vehicles shows the reader how to formulate and solve control problems which satisfy multiple objectives which may be arbitrary and complex with contradictory influences on fuel consumption emissions and drivability The text introduces industrial engineers postgraduates and researchers to the theory of hybrid optimal control problems A series of novel algorithmic developments provides tools for solving engineering problems of growing complexity in the field of hybrid vehicles Important topics of real relevance rarely found in text books and research publications switching costs sensitivity of discrete decisions and there impact on fuel savings etc are discussed and supported with practical applications

These demonstrate the contribution of optimal hybrid control in predictive energy management advanced powertrain calibration and the optimization of vehicle configuration with respect to fuel economy lowest emissions and smoothest drivability Numerical issues such as computing resources simplifications and stability are treated to enable readers to assess such complex systems To help industrial engineers and managers with project decision making solutions for many important problems in hybrid vehicle control are provided in terms of requirements benefits and risks *Topological Aspects of Nonsmooth Optimization* Vladimir Shikhman, 2011-11-18 This book deals with nonsmooth structures arising within the optimization setting It considers four optimization problems namely mathematical programs with complementarity constraints general semi infinite programming problems mathematical programs with vanishing constraints and bilevel optimization The author uses the topological approach and topological invariants of corresponding feasible sets are investigated Moreover the critical point theory in the sense of Morse is presented and parametric and stability issues are considered The material progresses systematically and establishes a comprehensive theory for a rather broad class of optimization problems tailored to their particular type of nonsmoothness *Topological Aspects of Nonsmooth Optimization* will benefit researchers and graduate students in applied mathematics especially those working in optimization theory nonsmooth analysis algebraic topology and singularity theory **Subject Guide to Books in Print** ,1993 **Proceedings of the 33rd IEEE Conference on Decision and Control** ,1994

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