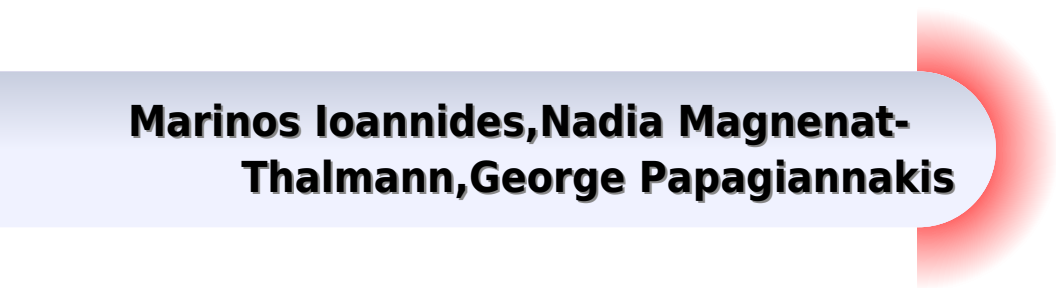


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Raja Chatila (Eds.)**

Autonomous Navigation in Dynamic Environments

Autonomous Navigation In Dynamic Environments Springer Tracts In Advanced Robotics

**Marinos Ioannides, Nadia Magnenat-
Thalmann, George Papagiannakis**



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Motion Planning Xj Jing, 2008-06-01 In this book new results or developments from different research backgrounds and application fields are put together to provide a wide and useful viewpoint on these headed research problems mentioned above focused on the motion planning problem of mobile robots These results cover a large range of the problems that are frequently encountered in the motion planning of mobile robots both in theoretical methods and practical applications including obstacle avoidance methods navigation and localization techniques environmental modelling or map building methods and vision signal processing etc Different methods such as potential fields reactive behaviours neural fuzzy based methods motion control methods and so on are studied Through this book and its references the reader will definitely be able to get a thorough overview on the current research results for this specific topic in robotics The book is intended for the readers who are interested and active in the field of robotics and especially for those who want to study and develop their own methods in motion path planning or control for an intelligent robotic system

Pattern Recognition José Francisco Martínez-Trinidad, Jesús Ariel Carrasco-Ochoa, Victor Ayala Ramírez, José Arturo Olvera-López, Xiaoyi Jiang, 2016-06-15 This book constitutes the refereed proceedings of the 8th Mexican Conference on Pattern Recognition MCPR 2016 held in Guanajuato Mexico in June 2016 The 34 revised full papers presented were carefully reviewed and selected from 60 submissions The papers are organized in topical sections on computer vision and image analysis pattern recognition and artificial intelligent techniques signal processing and analysis and applications of pattern recognition

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