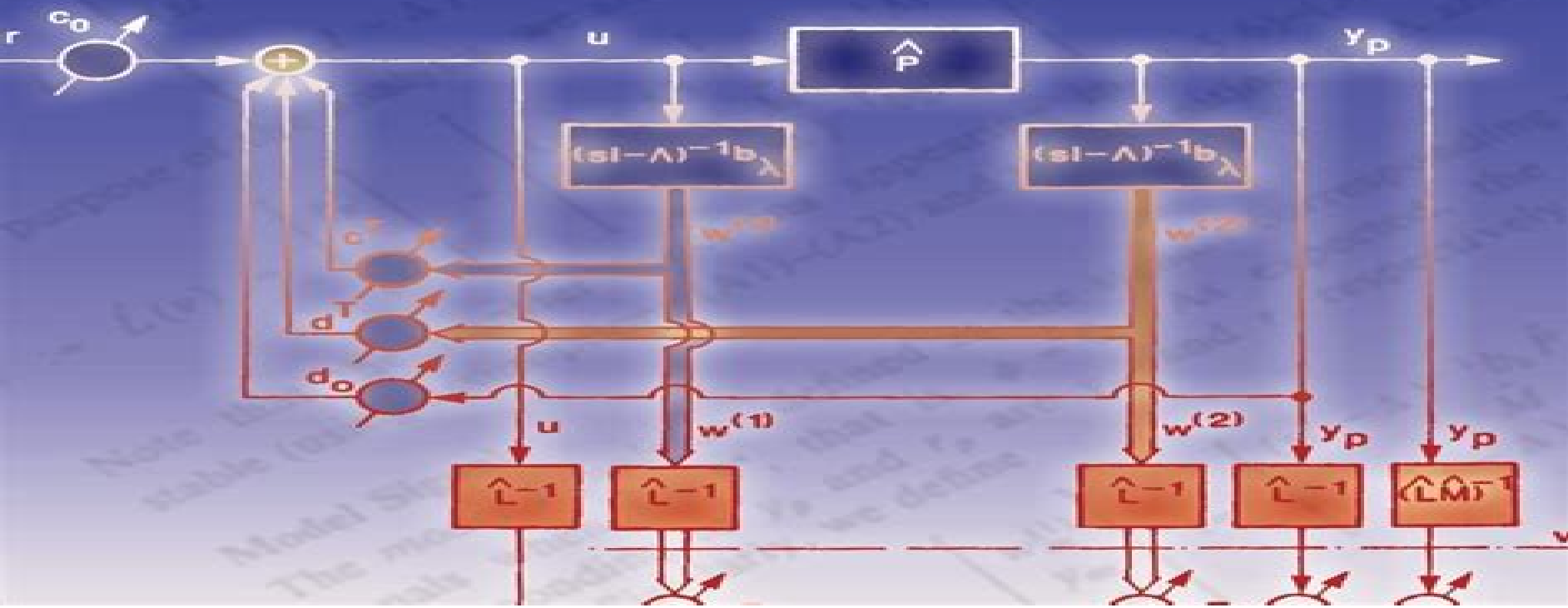


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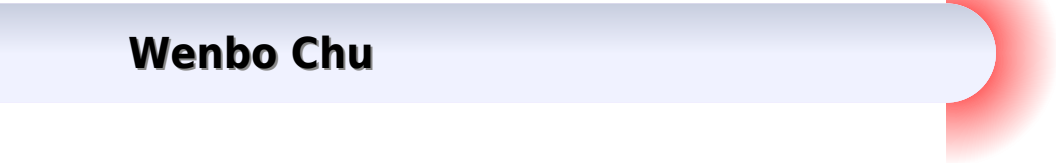
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regarding the vehicle states ensure more desirable vehicle motions and better robustness in unforeseeable driving environments. Given the impressive features of Distributed Electric Vehicles including their simple and compact structure, short transmission chains, fast and accurate control response, modular drivetrain design, etc., it is widely recognized that they represent an important future development direction and attract many of the brightest engineers and scientists. This book makes a significant contribution to the design of safer and more efficient vehicles. *Intelligent Electrical Systems*: Satyajit Chakrabarti, Ayan Kumar Panja, Amartya Mukherjee, Arun Kr. Bar, 2021-01-10. The conference aims to provide a premier platform for Engineers, researchers, scientists, and academicians to present their work in the emerging areas such as Renewable Energy, Energy storage, Power Electronics, drives, Smart devices and communication systems, Artificial Intelligence, Robotics, Networks, an IoT, Control and automation, etc.

Advanced Autonomous Vehicle Design for Severe Environments V.V. Vantsevich, M.V. Blundell, 2015-10-20. Classical vehicle dynamics, which is the basis for manned ground vehicle design, has exhausted its potential for providing novel design concepts to a large degree. At the same time, unmanned ground vehicle (UGV) dynamics is still in its infancy and is currently being developed using general analytical dynamics principles with very little input from actual vehicle dynamics theory. This technical book presents outcomes from the NATO Advanced Study Institute (ASI) Advanced Autonomous Vehicle Design for Severe Environments held in Coventry, UK, in July 2014. The ASI provided a platform for world-class professionals to meet and discuss leading-edge research, engineering accomplishments, and future trends in manned and unmanned ground vehicle dynamics, terrain mobility, and energy efficiency. The outcomes of this collective effort serve as an analytical foundation for autonomous vehicle design. Topics covered include historical aspects, pivotal accomplishments, and the analysis of future trends in on and off-road manned and unmanned vehicle dynamics, terramechanics, soil dynamic characteristics, uncertainties, and stochastic characteristics of vehicle environment interaction for agile vehicle dynamics modeling, new methods and techniques in on-line control and learning for vehicle autonomy, fundamentals of agility and severe environments, mechatronics and cyber physics issues of agile vehicle dynamics, to design for control, energy harvesting, and cyber security, and case studies of agile and inverse vehicle dynamics and vehicle systems design, including optimisation of suspension and driveline systems. The book targets graduate students who desire to advance further in leading-edge vehicle dynamics topics in manned and unmanned ground vehicles, PhD students continuing their research work, and building advanced curricula in academia and industry, and researchers in government agencies and private companies.

Sliding Mode Control and Observation Yuri Shtessel, Christopher Edwards, Leonid Fridman, Arie Levant, 2013-06-01. The sliding mode control methodology has proven effective in dealing with complex dynamical systems affected by disturbances, uncertainties, and unmodeled dynamics. Robust control technology based on this methodology has been applied to many real-world problems, especially in the areas of aerospace control, electric power systems, electromechanical systems, and robotics. Sliding Mode Control and Observation represents the first textbook that starts with

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