





Building Multicopter Video Drones

Ty Audronis

Building Multicopter Video Drones:

Building Multicopter Video Drones Ty Audronis, 2014-08-26 This book is for a wide range of individuals who are looking to shoot aerial footage with a multicopter No previous flying experience is assumed but even the most expert flyers will find **Designing Purpose-Built Drones for Ardupilot Pixhawk 2.1** Ty unexpected and interesting information Audronis, 2017-12-29 Design and build land air and sea drones using Ardupilot with Pixhawk 2 1 About This Book Explore the best practices used by the top industry professionals that will not only help you build drones in time but also build effective solutions to cater to Navigate through the complexities of Ardupilot to put together a complete functional UAV and assemble your drone Learn through practical examples that help you build robust UAV flight and ground control components Who This Book Is For The primary audience for this book is anyone enthusiasts and hobbyists who dream of building their own drones It will also help those who are trying to build UAVs for commercial purposes Some prior experience with microcontrollers and electronics would be useful What You Will Learn Kitbash dumb objects into smart ones Program Pixhawk for your drones Fabricate your own parts out of different materials Integrate Pixhawk into different types of drones Build and understand the significant difference between land sea and air drones Adapt old Pixhawk sensors to the new Pixhawk 2 1 plugs Become familiar with procedures for testing your new drones In Detail The Ardupilot platform is an application ecosystem that encompasses various OS projects for drone programming flight control and advanced functionalities The Ardupilot platform supports many Comms and APIs such as DroneKit ROS and MAVLink It unites OS drone projects to provide a common codebase With the help of this book you will have the satisfaction of building a drone from scratch and exploring its many recreational uses aerial photography playing aerial surveillance and so on This book helps individuals and communities build powerful UAVs for both personal and commercial purposes You will learn to unleash the Ardupilot technology for building monitoring and controlling your drones This is a step by step guide covering practical examples and instructions for assembling a drone building ground control unit using microcontrollers QgroundControl and MissionPlanner You can further build robotic applications on your drone utilizing critical software libraries and tools from the ROS framework With the help of DroneKit and MAVLink for reliable communication you can customize applications via cloud and mobile to interact with your UAV Style and approach Step by step instructions to help assemble your first drone with the Ardupilot platform ROS Robotics By Example Carol Fairchild, Dr. Thomas L. Harman, 2017-11-30 Learning how to build and program your own robots with the most popular open source robotics programming framework About This Book Get to know the fundamentals of ROS and apply its concepts to real examples Learn how to write robotics applications without getting bogged down in hardware problems Learn to implement best practices in ROS development Who This Book Is For This book is for robotic enthusiasts researchers and professional robotics engineers who would like to build robot applications using ROS It gives the robotics beginner and the ROS newbie an immensely practical introduction to robot building and robotics application coding Basic

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