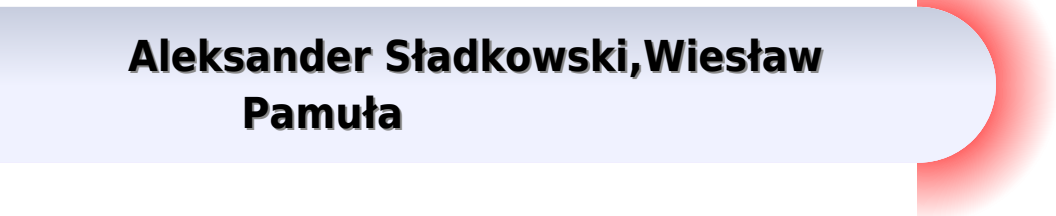




# Artificial Intelligence Motion Control Transport

**Aleksander Sładkowski, Wiesław  
Pamuła**



## **Artificial Intelligence Motion Control Transport:**

**Artificial Intelligence in Motion Control of Road Transport** Ianchelenko Viktor, Zagritcenko Aleksandr, Ivanov Sergey, 2015-12-11 The application of the artificial intelligence the expert systems of real time on vehicles with autonomous unmanned transport is examined The paper describes the development of mathematical models of car management development of the expert systems databases and methods of manipulation knowledge bases planning and implementation of multi factor performance tests technology design inference and obtaining management solutions All techniques are illustrated with examples of practical solutions to transport problems The work is intended for students which enrolled in the specialty Organization of transportation and management of transport road transport as well as specialists engaged in road transport of goods and passengers the creation and operation of the car with the artificial intelligence

**The Proceedings of 2024 International Conference on Artificial Intelligence and Autonomous Transportation** Limin Jia, Dechen Yao, Feng Ma, Liguang Zhang, Yuejian Chen, Qingwan Xue, 2025-03-27 This book reflects the latest research trends methods and experimental results in the field of Artificial Intelligence and Autonomous Transportation which covers abundant state of the art research theories and ideas As a vital research area that is highly relevant to current developments in a number of technological domains the topics covered include Autonomous Transportation Systems Autonomous Transportation Management and Control Technology Autonomous Transportation Equipment Technology Vehicular Networking and Information Security Emerging Technologies and Future Mobility Intelligent water transportation technology Cross Domain Transportation Technology and so on The goal of the proceedings is to provide a major interdisciplinary forum for researchers engineers academics and industry professionals to present the most innovative research and development in the field of Artificial Intelligence and Autonomous Transportation Engineers and researchers from academia industry and government will also explore an insight view of the solutions that combine ideas from multiple disciplines in this area The volumes serve as an excellent reference work for researchers and graduate students working in the areas of rail transportation electrical engineering and information technology

**Using Artificial Intelligence to Solve Transportation Problems** Aleksander Ślaskowski, 2024-12-14 This book focuses on the role of Artificial Intelligence in solving transportation problems and presents papers from around the world on AI in transportation Currently the development of computer technology and software has led to what can be said to be the beginning of a fundamentally new stage in science and technology This new level is called Artificial Intelligence AI AI can be used in any area of human activity One of the broadest uses of AI comes from transportation broadly understood Obviously it is impossible to present all the possibilities of AI in the field of design production and operation of transport in one book But the authors of this monothematic monograph tried to describe achievements in their areas In particular the use of AI allows you to save energy and fuel when using vehicles improve the preparation and implementation of transport processes simplify warehouse

operations analyze and modernize existing transport infrastructure These and other aspects of the use of AI in the transport industry are discussed in the monograph by specialists from Greece China Poland and other countries This book can be recommended for study by scientists and professionals It can also be selected by teachers as additional material when preparing relevant courses Moreover it can also be recommended for any readers seriously interested in the transportation industry

**The Proceedings of 2024 International Conference on Artificial Intelligence and Autonomous Transportation** Jun Liu,Jianjian Yang,Minyi Xu,Quan Yu,Wenchao Shen,2025-03-27 This book reflects the latest research trends methods and experimental results in the field of Artificial Intelligence and Autonomous Transportation which covers abundant state of the art research theories and ideas As a vital research area that is highly relevant to current developments in a number of technological domains the topics covered include Autonomous Transportation Systems Autonomous Transportation Management and Control Technology Autonomous Transportation Equipment Technology Vehicular Networking and Information Security Emerging Technologies and Future Mobility Intelligent water transportation technology Cross Domain Transportation Technology and so on The goal of the proceedings is to provide a major interdisciplinary forum for researchers engineers academics and industry professionals to present the most innovative research and development in the field of Artificial Intelligence and Autonomous Transportation Engineers and researchers from academia industry and government will also explore an insight view of the solutions that combine ideas from multiple disciplines in this area The volumes serve as an excellent reference work for researchers and graduate students working in the areas of rail transportation electrical engineering and information technology

**Handbook on Artificial Intelligence and Transport** Hussein Dia,2023-10-06 With AI advancements eliciting imminent changes to our transport systems this enlightening Handbook presents essential research on this evolution of the transportation sector It focuses on not only urban planning but relevant themes in law and ethics to form a unified resource on the practicality of AI use

Artificial Intelligence and Soft Computing Leszek Rutkowski,Rafał Scherer,Marcin Korytkowski,Witold Pedrycz,Ryszard Tadeusiewicz,Jacek M. Zurada,2018-05-24 The two volume set LNAI 10841 and LNAI 10842 constitutes the refereed proceedings of the 17th International Conference on Artificial Intelligence and Soft Computing ICAISC 2018 held in Zakopane Poland in June 2018 The 140 revised full papers presented were carefully reviewed and selected from 242 submissions The papers included in the second volume are organized in the following five parts computer vision image and speech analysis bioinformatics biometrics and medical applications data mining artificial intelligence in modeling simulation and control and various problems of artificial intelligence

**Internet of Things and Artificial Intelligence in Transportation Revolution** Miltiadis D. Lytras,Kwok Tai Chui,Ryan Wen Liu,2021-04-14 The advent of Internet of Things offers a scalable and seamless connection of physical objects including human beings and devices This along with artificial intelligence has moved transportation towards becoming intelligent transportation This book is a collection of eleven articles

that have served as examples of the success of internet of things and artificial intelligence deployment in transportation research Topics include collision avoidance for surface ships indoor localization vehicle authentication traffic signal control path planning of unmanned ships driver drowsiness and stress detection vehicle density estimation maritime vessel flow forecast and vehicle license plate recognition High performance computing services have become more affordable in recent years which triggered the adoption of deep learning based approaches to increase the performance standards of artificial intelligence models Nevertheless it has been pointed out by various researchers that traditional shallow learning based approaches usually have an advantage in applications with small datasets The book can provide information to government officials researchers and practitioners In each article the authors have summarized the limitations of existing works and offered valuable information on future research directions

**Advanced Motion Control and Navigation of Robots in Extreme Environments** Allahyar Montazeri, Nargess Sadeghzadeh-Nokhodberiz, Khoshnam Shojaei, Kaspar

Althoefer, 2024-11-20 Advances in robotics and autonomous systems have opened new horizons for the scientists by creating new opportunities to explore extreme environments that would previously not have been possible For example robots that are deployed to study environmental processes such remote volcanos monitor the climate variables under the adverse weather conditions understand underground mines and explore deep oceans which are all inaccessible or hazardous for the human Industrial applications can also often be situated in extreme environments such as offshore oil and gas and nuclear industries In such applications the autonomous robot is expected to complete tasks such as repair and maintenance exploration reconnaissance inspection and transportation which is either done in isolation or as a team of cooperative robots Due to the harsh and severe conditions of such environments designing an advanced robotic system that can endure them is a challenging task The robot needs to cope with the time varying restricted uncertain and unstructured nature of the environment to achieve the planning and execution of the tasks This in turn demands development of advanced robust and adaptive motion control and navigation algorithms along with machine learning and deep learning algorithms with high cognitive capability for the robot to perceive the surrounding environment effectively The use of both single and multi robot platforms can be advantageous depending on the specific application and environment

Intelligent Transportation Systems – Problems and Perspectives Aleksander Ślădkowski, Wiesław Pamuła, 2015-06-24 This book presents a discussion of problems encountered in the deployment of Intelligent Transport Systems ITS It puts emphasis on the early tasks of designing and proofing the concept of integration of technologies in Intelligent Transport Systems In its first part the book concentrates on the design problems of urban ITS The second part of the book features case studies representative for the different modes of transport These are freight transport rail transport and aerospace transport encompassing also space stations The book provides ideas for deployment which may be developed by scientists and engineers engaged in the design of Intelligent Transport Systems It can also be used in the training of specialists students and post graduate students in

universities and transport high schools      **Advanced Motion Control and Sensing for Intelligent Vehicles** Li Li, Fei-Yue Wang, 2007-11-24 Advanced Motion Control and Sensing for Intelligent Vehicles provides the latest information in intelligent vehicle control sensing and intelligent transportation It addresses the growing need for safe comfortable time and energy efficient modes of transportation with emphasis on the latest key findings current trends and likely future developments in this rapidly expanding field Highlights Discusses individual vehicle dynamics sensory and multiple ground vehicle interactions Includes systematic review of past and current research achievements Presents case studies in cutting edge directions such as vehicle steering motion vehicle vision systems cooperative driving intersection safety and tire pressure monitoring Assesses the likely future developments of this field This book is useful for both practicing engineers and researchers in the automotive industry

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