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Autodesk Inventor Professional Training Manual

Randy Shih



Autodesk Inventor Professional Training Manual:

Autodesk Inventor 2023 Cookbook Alexander Bordino, 2022-11-30 With a recipe based approach hone and develop the necessary skills you need to perform mechanical visualization and simulation tasks using Autodesk Inventor Key Features Create powerful parametric 3D designs parts and assemblies Apply effective modeling techniques to increase automation and promote configuration Enable iLogic powered rapid configurations and apply Finite Element Analysis for model simulation Book Description Autodesk Inventor is an industry leading computer aided design application for 3D mechanical design simulation visualization and documentation This book will help to bridge the gap between the fundamentals of this software and the more advanced features workflows and environments it has to offer Using cookbook style recipes you ll gain a comprehensive understanding and practical experience in creating dynamic 3D parts assemblies and complete designs You ll also explore a variety of topics including automation and parametric techniques collaboration tools creating sheet metal designs and design accelerators such as frame generators As you progress the chapters will guide you through surface modeling tools advanced assembly and simplification tools along with covering iLogic Finite Element Analysis and more By the end of this book you ll not only be able to use the advanced functionality within Autodesk Inventor but also have the practical experience you need to deploy specific techniques in your own projects and workflows What you will learn Build upon the fundamentals of parts assemblies and drawings Understand how to use advanced modeling tools such as iFeatures iLogic and more Develop your experience with parametric design methodologies Explore surface modeling and project management techniques Design efficiently with design accelerators to drive automation Understand and apply Finite Element Analysis Who this book is for This book is for CAD engineers mechanical design engineers and product designers who have a basic understanding and experience of Inventor fundamentals It aims to guide and coach you past the basics and into the advanced functionality of the software and environments within it *Learning Autodesk Inventor 2025* Randy Shih, 2024-07 Teaches beginners how to use Autodesk Inventor with easy to understand tutorials Features a simple robot design used as a project throughout the book Covers modeling gear creation linkage analysis assemblies simulations and 3D animation Available with an optional robot kit This book will teach you everything you need to know to start using Autodesk Inventor 2025 with easy to understand step by step tutorials This book features a simple robot design used as a project throughout the book You will learn to model parts create assemblies run simulations and even create animations of your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become

familiar with many of Inventor's powerful tools and commands that enable you to easily construct complex features in your models. Also included is coverage of gears, gear trains, and spur gear creation using Autodesk Inventor. This book continues by examining the different mechanisms commonly used in walking robots. You will learn the basic types of planar four-bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages. Using the knowledge you gained about linkages and mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book, you learn how to combine all the robot parts into assemblies and then run motion analysis. You will finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks with Autodesk Inventor, but this book takes you through an entire project and shows you the complete engineering process. By the end of this book, you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot.

Learning Autodesk Inventor 2023 Randy Shih, 2022-07. This book will teach you everything you need to know to start using Autodesk Inventor 2023 with easy-to-understand, step-by-step tutorials. This book features a simple robot design used as a project throughout the book. You will learn to model parts, create assemblies, run simulations, and even create animations of your robot design. An unassembled version of the same robot used throughout the book can be bundled with the book. No previous experience with Computer Aided Design (CAD) is needed since this book starts at an introductory level. The author begins by getting you familiar with the Inventor interface and its basic tools. You will start by learning to model simple robot parts, and before long, you will graduate to creating more complex parts and multi-view drawings. Along the way, you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships. You will also become familiar with many of Inventor's powerful tools and commands that enable you to easily construct complex features in your models. Also included is coverage of gears, gear trains, and spur gear creation using Autodesk Inventor. This book continues by examining the different mechanisms commonly used in walking robots. You will learn the basic types of planar four-bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages. Using the knowledge you gained about linkages and mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book, you learn how to combine all the robot parts into assemblies and then run motion analysis. You will finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks with Autodesk Inventor, but this book takes you through an entire project and shows you the complete engineering process. By the end of this book, you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot.

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mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot

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your robot design An unassembled version of the same robot used throughout the book can be bundled with the book No previous experience with Computer Aided Design CAD is needed since this book starts at an introductory level The author begins by getting you familiar with the Inventor interface and its basic tools You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi view drawings Along the way you will learn the fundamentals of parametric modeling through the use of geometric constraints and relationships You will also become familiar with many of Inventor s powerful tools and commands that enable you to easily construct complex features in your models Also included is coverage of gears gear trains and spur gear creation using Autodesk Inventor This book continues by examining the different mechanisms commonly used in walking robots You will learn the basic types of planar four bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages Using the knowledge you gained about linkages and mechanism you will learn how to modify your robot and change its behavior by modifying or creating new parts In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis You will finish off your project by creating 3D animations of your robot in action There are many books that show you how to perform individual tasks with Autodesk Inventor but this book takes you through an entire project and shows you the complete engineering process By the end of this book you will have modeled and assembled nearly all the parts that make up the TAMIYA Mechanical Tiger and can start building your own robot

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