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Control of nonlinear differential algebraic equation systems



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Algebraic Methods For Nonlinear Control Systems

Algebraic Methods For Nonlinear Control Systems

Bongsob Song, J. Karl Hedrick



Algebraic Methods For Nonlinear Control Systems Algebraic Methods For Nonlinear Control Systems:

Algebraic Methods for Nonlinear Control Systems Giuseppe Conte, Claude H. Moog, Anna Maria Perdon, 2007-01-19
A self contained introduction to algebraic control for nonlinear systems suitable for researchers and graduate students
Algebraic Methods for Nonlinear Control Systems develops a linear algebraic alternative to the usual differential geometric approach to nonlinear control using vector spaces over suitable fields of nonlinear functions It describes a range of results some of which can be derived using differential geometry but many of which cannot They include classical and generalized realization in the nonlinear context accessibility and observability recast for the linear algebraic setting discussion and solution of basic feedback problems results for dynamic and static state and output feedback Dynamic feedback and realization are shown to be dealt with and solved much more easily in the algebraic framework The second edition has been completely revised with new text examples and exercises it is divided into two parts necessary methodology and applications to control problems

Algebraic Methods for Nonlinear Control Systems Giuseppe Conte, Claude H. Moog, Anna Maria Perdon, 2009-10-12 This is a self contained introduction to algebraic control for nonlinear systems suitable for researchers and graduate students It is the first book dealing with the linear algebraic approach to nonlinear control systems in such a detailed and extensive fashion It provides a complementary approach to the more traditional differential geometry and deals more easily with several important characteristics of nonlinear systems

Nonlinear Control Systems G. Conte, C.H. Moog, A.M. Perdon, 2014-03-12 This book provides a unique and alternative approach to the study of nonlinear control systems with applications The approach presented is based on the use of algebraic methods which are intrinsically linear rather than differential geometric methods which are more commonly found in other reference works on the subject This allows the exposition to remain simple from a mathematical point of view and accessible for everyone who has a good understanding of linear control theory The book is divided into the following three parts Part 1 is devoted to mathematical preliminaries and to the development of tools and methods for system analysis Part 2 is concerned with solving specific control problems including disturbance decoupling non interactive control model matching and feedback linearization problems Part 3 introduces differential algebraic notions and discusses their applications to nonlinear control and system theory With numerous examples used to illustrate theoretical results this self contained and comprehensive volume will be of interest to all those who have a good basic knowledge of standard linear control systems

Nonlinear Control Systems II Alberto Isidori, 1999-09-22 This eagerly awaited follow up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws for the purpose of globally stabilizing nonlinear systems via state or output feedback The author is one of the most prominent researchers in the field

Nonlinear Control Systems Design 1989 A. Isidori, 2014-05-23 In the last two decades the development of specific methodologies for the control of systems described by nonlinear mathematical models has attracted an ever increasing interest New breakthroughs have occurred which have aided the

design of nonlinear control systems However there are still limitations which must be understood some of which were addressed at the IFAC Symposium in Capri The emphasis was on the methodological developments although a number of the papers were concerned with the presentation of applications of nonlinear design philosophies to actual control problems in chemical electrical and mechanical engineering

Algebraic and Geometric Methods in Nonlinear Control Theory M. Fliess, Michiel Hazewinkel, 2012-12-06 Approach your problems from the right end It isn't that they can't see the solution It is and begin with the answers Then one day that they can't see the problem perhaps you will find the final question G K Chesterton The Scandal of Father The Hermit Clad in Crane Feathers in R Brown The point of a Pin van Gulik's The Chinese Maze Murders Growing specialization and diversification have brought a host of monographs and textbooks on increasingly specialized topics However the tree of knowledge of mathematics and related fields does not grow only by putting forth new branches It also happens quite often in fact that branches which were thought to be completely disparate are suddenly seen to be related Further the kind and level of sophistication of mathematics applied in various sciences has changed drastically in recent years measure theory is used non trivially in regional and theoretical economics algebraic geometry interacts with physics the Minkowski lemma coding theory and the structure of water meet one another in packing and covering theory quantum fields crystal defects and mathematical programming profit from homotopy theory Lie algebras are relevant to filtering and prediction and electrical engineering can use Stein spaces And in addition to this there are such new emerging subdisciplines as experimental mathematics CFD completely integrable systems chaos synergetics and large scale order which are almost impossible to fit into the existing classification schemes They draw upon widely different sections of mathematics

Nonlinear Control Systems Alberto Isidori, 2013-04-17 The purpose of this book is to present a self contained description of the fundamentals of the theory of nonlinear control systems with special emphasis on the differential geometric approach The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems The first version of this book was written in 1983 while I was teaching at the Department of Systems Science and Mathematics at Washington University in St Louis This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana Champaign in 1987 at the Carl Cranz Gesellschaft in Oberpfaffenhofen in 1987 at the University of California in Berkeley in 1988 In addition to a major rearrangement of the last two Chapters of the first version this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985

Control of Nonlinear Dynamical Systems Felix L. Chernous'ko, I. M. Ananievski, S. A. Reshmin, 2008-09-26 This book is devoted to new methods of control for complex dynamical systems and deals with nonlinear control systems having several degrees of freedom subjected to unknown disturbances and containing uncertain parameters Various constraints are imposed on control inputs and state variables or their combinations The book contains an introduction to the theory of optimal control and the

theory of stability of motion and also a description of some known methods based on these theories Major attention is given to new methods of control developed by the authors over the last 15 years Mechanical and electromechanical systems described by nonlinear Lagrange's equations are considered General methods are proposed for an effective construction of the required control often in an explicit form The book contains various techniques including the decomposition of nonlinear control systems with many degrees of freedom piecewise linear feedback control based on Lyapunov's functions methods which elaborate and extend the approaches of the conventional control theory optimal control differential games and the theory of stability The distinctive feature of the methods developed in the book is that the controls obtained satisfy the imposed constraints and steer the dynamical system to a prescribed terminal state in finite time Explicit upper estimates for the time of the process are given In all cases the control algorithms and the estimates obtained are strictly proven

Fundamentals of Control Engineering Aniruddh Mohan, 2025-02-20 Fundamentals of Control Engineering explores the evolving landscape of control engineering covering classical principles and advanced methodologies Authored by experts this book provides a comprehensive understanding of control systems principles applications and challenges It adopts a multifaceted approach covering classical control theory modern strategies and specialized topics like quantum control intelligent systems and biomedical control Each chapter balances theoretical principles with practical applications making it suitable for students researchers and engineers The inclusion of advanced topics such as quantum control and intelligent systems reflects emerging technologies reshaping the field Practical examples and case studies showcase control engineering's relevance in various industries while interdisciplinary perspectives emphasize integrating control principles with fields like AI quantum mechanics and healthcare The book also addresses ethical considerations reliability issues and quantum coherence providing a holistic view of the field's opportunities and hurdles Fundamentals of Control Engineering is a valuable resource for understanding the multidisciplinary facets of control systems ideal for students researchers and professionals

Dynamic Surface Control of Uncertain Nonlinear Systems Bongsob Song, J. Karl Hedrick, 2011-05-16 Although the problem of nonlinear controller design is as old as that of linear controller design the systematic design methods framed in response are more sparse Given the range and complexity of nonlinear systems effective new methods of control design are therefore of significant importance Dynamic Surface Control of Uncertain Nonlinear Systems provides a theoretically rigorous and practical introduction to nonlinear control design The convex optimization approach applied to good effect in linear systems is extended to the nonlinear case using the new dynamic surface control DSC algorithm developed by the authors A variety of problems DSC design output feedback input saturation and fault tolerant control among them are considered The inclusion of applications material demonstrates the real significance of the DSC algorithm which is robust and easy to use for nonlinear systems with uncertainty in automotive and robotics Written for the researcher and graduate student of nonlinear control theory this book will provide the applied mathematician and engineer alike with a set of powerful tools for nonlinear control

design It will also be of interest to practitioners working with a mechatronic systems in aerospace manufacturing and automotive and robotics milieux

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